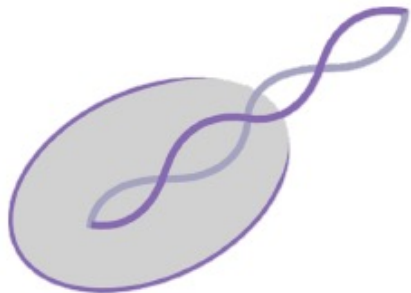


Stoichiometric mechanisms for oscillations and multistability in reaction networks

Nicola Vassena



UNIVERSITÄT
LEIPZIG

2^{1/2} preventive apologies

- MOST OF THE ARGUMENTS ARE IMPRECISE
- MOST OF THE ARGUMENTS ARE INCOMPLETE

...the pictures are a bit random



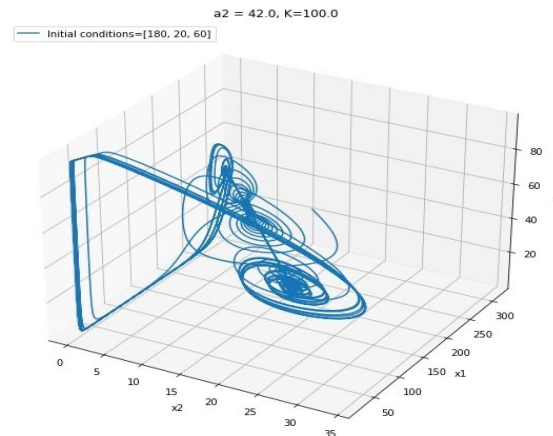
Motivation:

FIND

UNIVERSAL STOICHIOMETRIC PATTERNS FOR COMPLEX DYNAMICS

“UNIVERSAL” = VALID FOR ANY SIZE OF NETWORK

“COMPLEX DYNAMICS” = Multistability, Superlinear growth, Oscillations





MULTISTABILITY “=>” SUPERLINEAR GROWTH

Ingredient: unstable manifold theorem

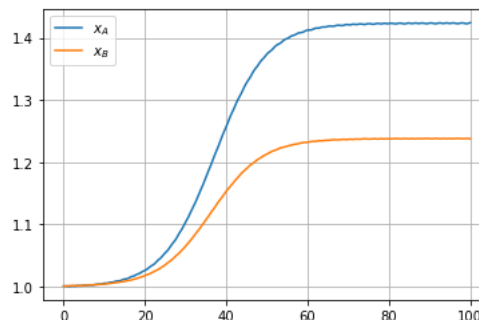


Multistability =>

unstable steady state connected to stable steady state =>

Superlinear divergence from unstable steady state

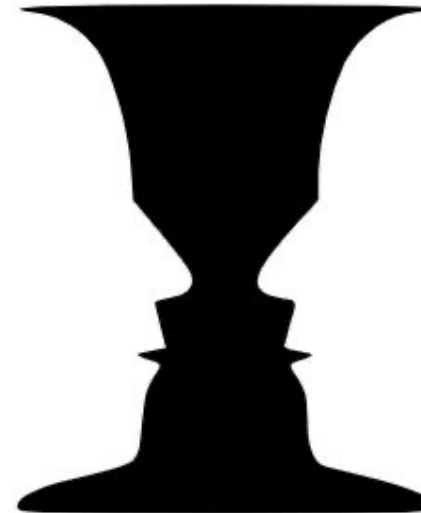
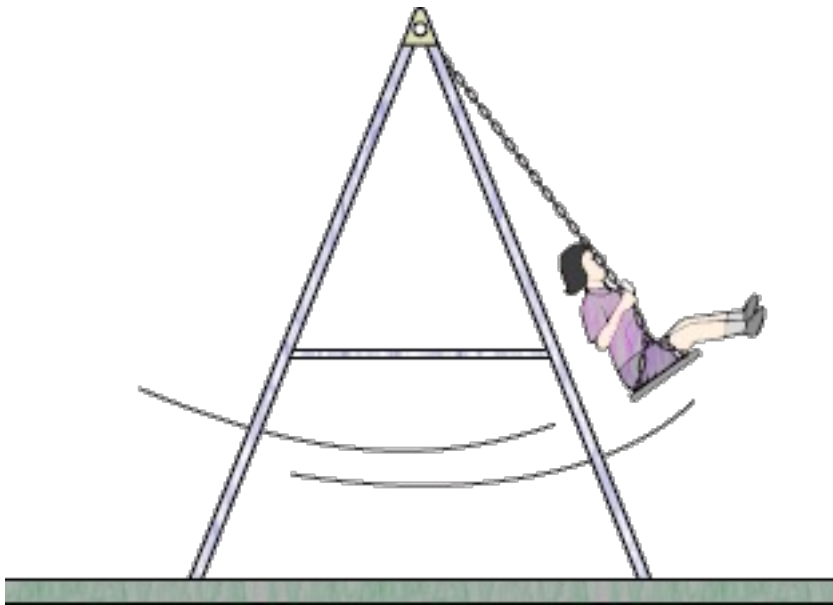
with sublinear convergence to the stable steady state =>



Two mechanisms

RECEIPT 1: Oscillations and Multistability

RECEIPT 2: Oscillations



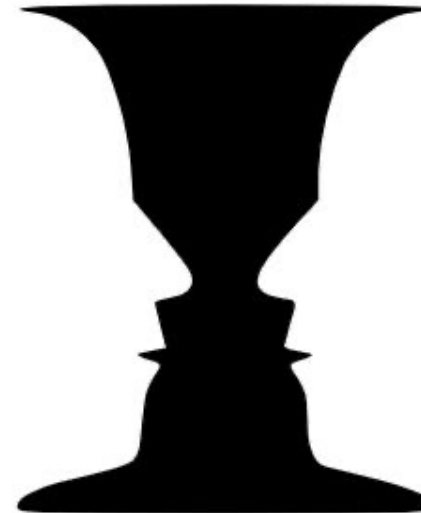
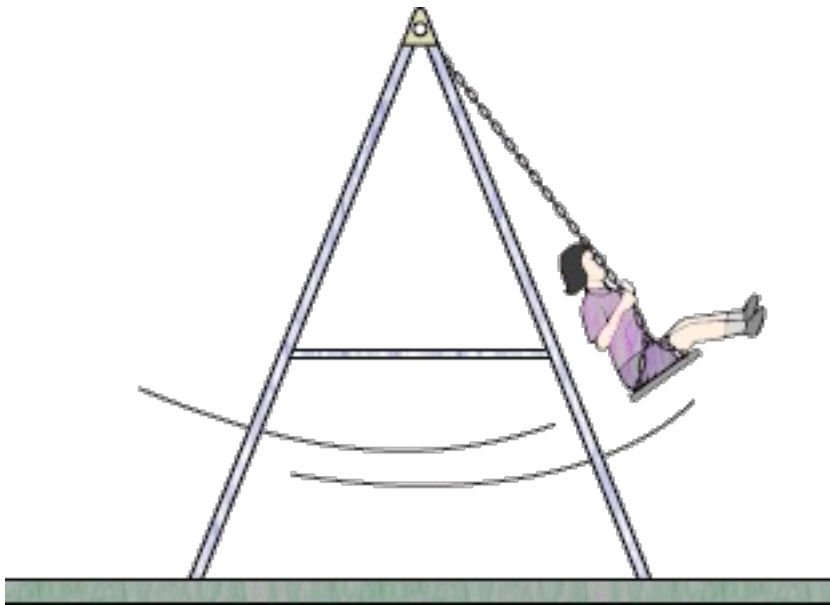
References (2023):

1. Symbolic Hunt ...
2. [With Peter] Unstable Cores ...

WARNING!
Multistability vs Multistationarity
Stable oscillations?

RECEIPT 1: Oscillations and Multistability

RECEIPT 2: Oscillations



References (2023):

1. Symbolic Hunt ...
2. [With Peter] Unstable Cores ...

RECEIPT 1 for Oscillations and Multistability

START WITH A SQUARE STOICHIOMETRIC SUBMATRIX
WITH NEGATIVE DIAGONAL AND DETERMINANT OF UNSTABLE SIGN

$$\begin{pmatrix} -1 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & -1 \end{pmatrix}$$

“Determinant of unstable sign”=odd number of eigenvalues with positive real part
(unstable core)(unstable positive feedback)(autocatalytic core)

Eigenvalues: $-1.66+0.56i$, $-1.66+0.56i$, 0.32

Dichotomy

Is such unstable `positive-feedback' a principal submatrix of a Hurwitz-stable stoichiometric submatrix with negative diagonal?

Yes. OSCILLATIONS

No. MULTISTATIONARITY

Dichotomy. Yes.

OSCILLATIONS

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 2 \\ 1 & 1 & -1 & 0 \\ 0 & 0 & -1 & -1 \end{pmatrix}$$

Eigenvalues: $-0.34+0.56i$, $-0.34-0.56i$, -1 , -2.32


Dichotomy. No. Multistationarity.

$$\begin{pmatrix} -1 & 0 & 1 & 0 & 0 & \dots & 0 \\ 1 & -1 & 0 & 0 & 0 & \dots & 0 \\ 1 & 1 & -1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & -1 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & -1 & \dots & 0 \\ 0 & 0 & 0 & 0 & 0 & \dots & -1 \end{pmatrix}$$

Dichotomy. No. Multistationarity.

“Papers” generalization:

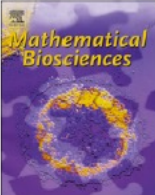
Maximal unstable
positive feedback
+
stable steady-state
 \Leftrightarrow
multistationarity



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Concordant chemical reaction networks

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^bThe William G. Lowrie Department of Chemical & Biomolecular Engineering and Department of Mathematics, Ohio State University, 140 W. 19th Avenue, Columbus, OH 43210, USA

SIAM Journal on Applied Dynamical Systems → Vol. 15, Iss. 2 (2016) → 10.1137/15M1034441

Some Results on Injectivity and Multistationarity in Chemical Reaction Networks

Authors: Murad Banaji and Casian Pantea | [AUTHORS INFO & AFFILIATIONS](#)

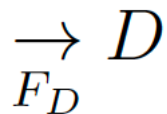
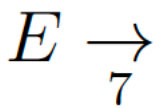
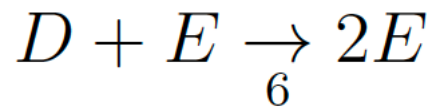
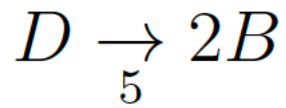
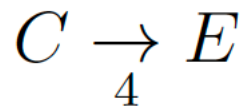
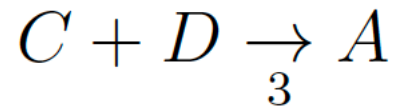
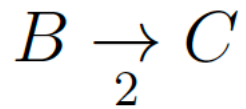
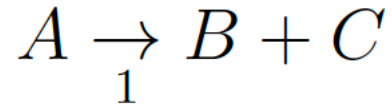
SIAM J. APPLIED DYNAMICAL SYSTEMS
Vol. 22, No. 3, pp. 1639–1672

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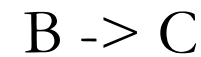
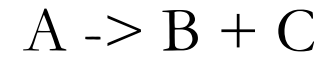
Structural Conditions for Saddle-Node Bifurcations in Chemical Reaction Networks*

Nicola Vassena[†]

Example for receipt 1.



CONTAINS:



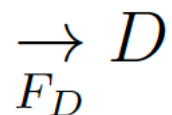
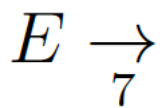
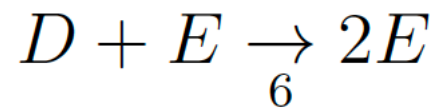
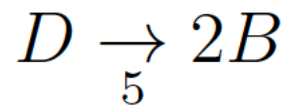
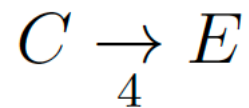
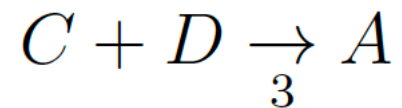
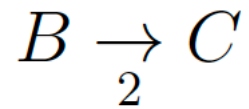
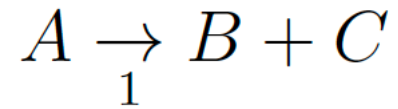
Stoichiometrically our

$$\begin{pmatrix} -1 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 1 & -1 \end{pmatrix}$$

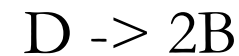
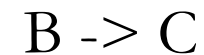
REFERENCE: “Symbolic Hunt...”

non autocatalytic version in “Unstable cores...” (with Peter)

Example for receipt 1: Oscillations



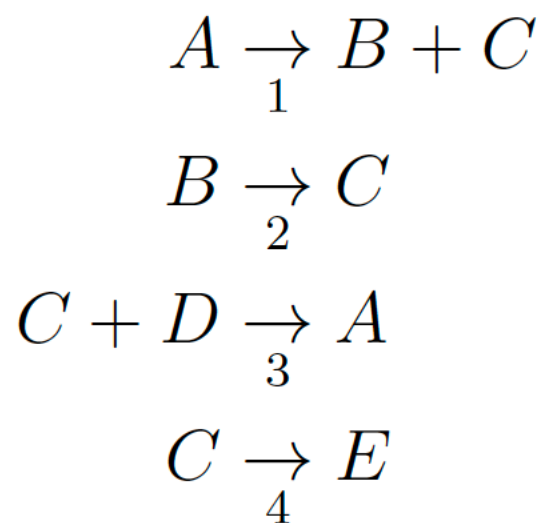
CONTAINS:



Stoichiometrically our

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 2 \\ 1 & 1 & -1 & 0 \\ 0 & 0 & -1 & -1 \end{pmatrix}$$

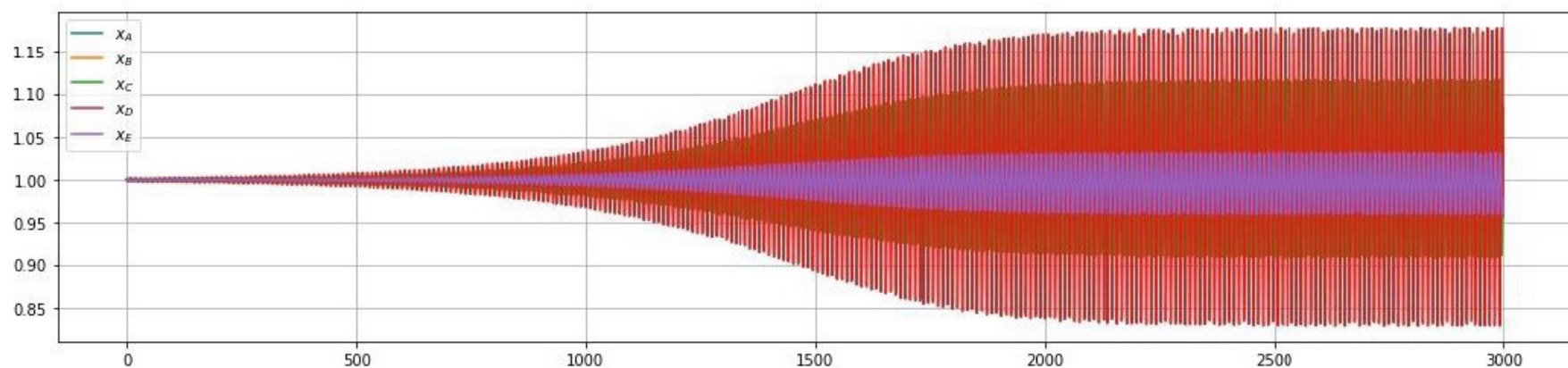
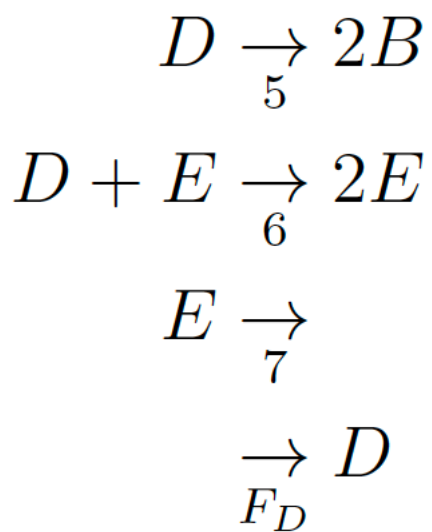
Example for receipt 1: Oscillations



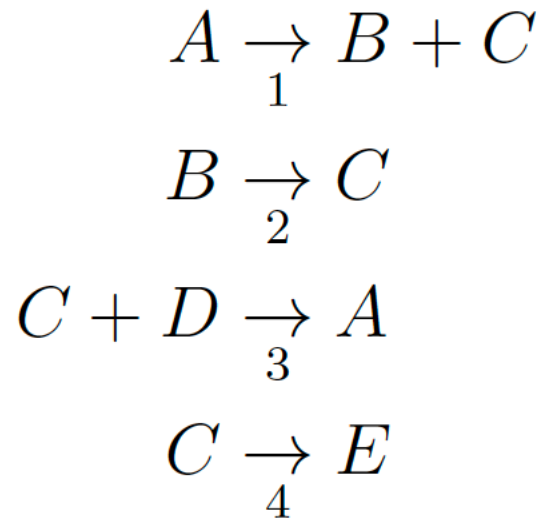
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 \dot{x}_B = r_1(x_A) - r_2(x_B) + 2r_5(x_D) \\
 \dot{x}_C = r_1(x_A) + r_2(x_B) - r_3(x_C, x_D) - r_4(x_C) \\
 \dot{x}_D = -r_3(x_C, x_D) - r_5(x_D) - r_6(x_D, x_E) + F_D \\
 \dot{x}_E = r_4(x_C) + r_6(x_D, x_E) - r_7(x_E)
 \end{cases}$$

$$\begin{pmatrix}
 r_1(x_A) \\
 r_2(x_B) \\
 r_3(x_C, x_D) \\
 r_4(x_C) \\
 r_5(x_D) \\
 r_6(x_D, x_E) \\
 r_7(x_E) \\
 F_D
 \end{pmatrix} = \begin{pmatrix}
 2x_A \\
 8\frac{x_B}{1+x_B} \\
 8\frac{x_C x_D}{1+3x_D} \\
 64\frac{x_C}{1+15x_C} \\
 2\frac{x_D}{1+x_D} \\
 512\frac{x_D}{1+63x_D} \frac{x_E}{1+3x_E} \\
 72\frac{x_E}{1+11x_E} \\
 5
 \end{pmatrix}$$

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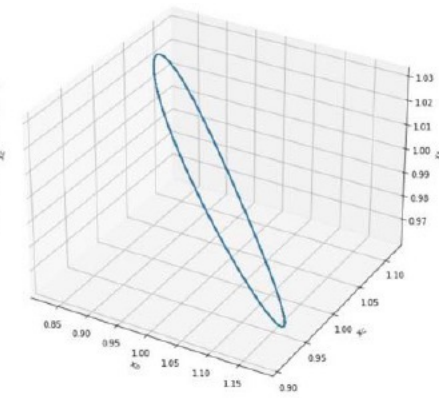
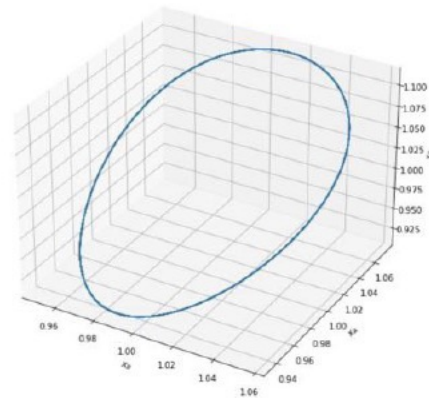
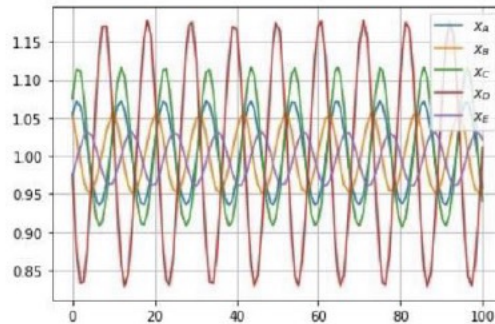
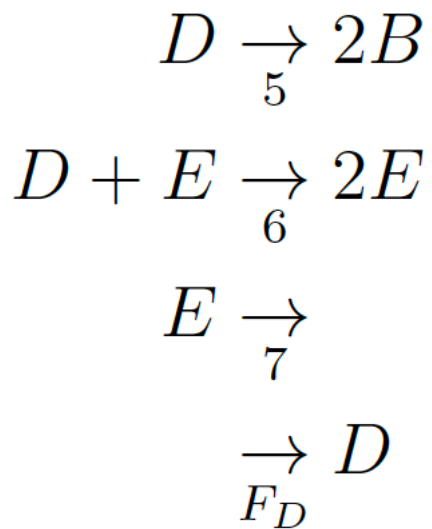
Example for receipt 1: Oscillations



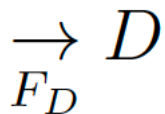
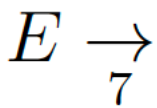
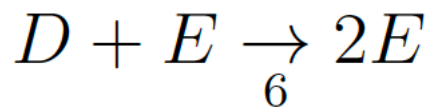
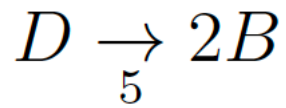
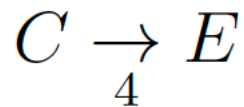
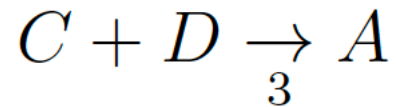
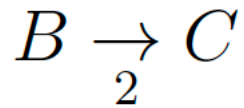
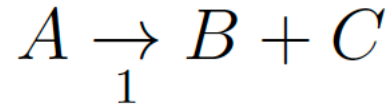
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 \dot{x}_B = r_1(x_A) - r_2(x_B) + 2r_5(x_D) \\
 \dot{x}_C = r_1(x_A) + r_2(x_B) - r_3(x_C, x_D) - r_4(x_C) \\
 \dot{x}_D = -r_3(x_C, x_D) - r_5(x_D) - r_6(x_D, x_E) + F_D \\
 \dot{x}_E = r_4(x_C) + r_6(x_D, x_E) - r_7(x_E)
 \end{cases}$$

$$\begin{pmatrix}
 r_1(x_A) \\
 r_2(x_B) \\
 r_3(x_C, x_D) \\
 r_4(x_C) \\
 r_5(x_D) \\
 r_6(x_D, x_E) \\
 r_7(x_E) \\
 F_D
 \end{pmatrix} = \begin{pmatrix}
 2x_A \\
 8\frac{x_B}{1+x_B} \\
 8\frac{x_C x_D}{1+3x_D} \\
 64\frac{x_C}{1+15x_C} \\
 2\frac{x_D}{1+x_D} \\
 512\frac{x_D}{1+63x_D} \frac{x_E}{1+3x_E} \\
 72\frac{x_E}{1+11x_E} \\
 5
 \end{pmatrix}$$

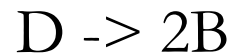
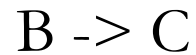
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Example for receipt 1: Multistationarity



CONTAINS:

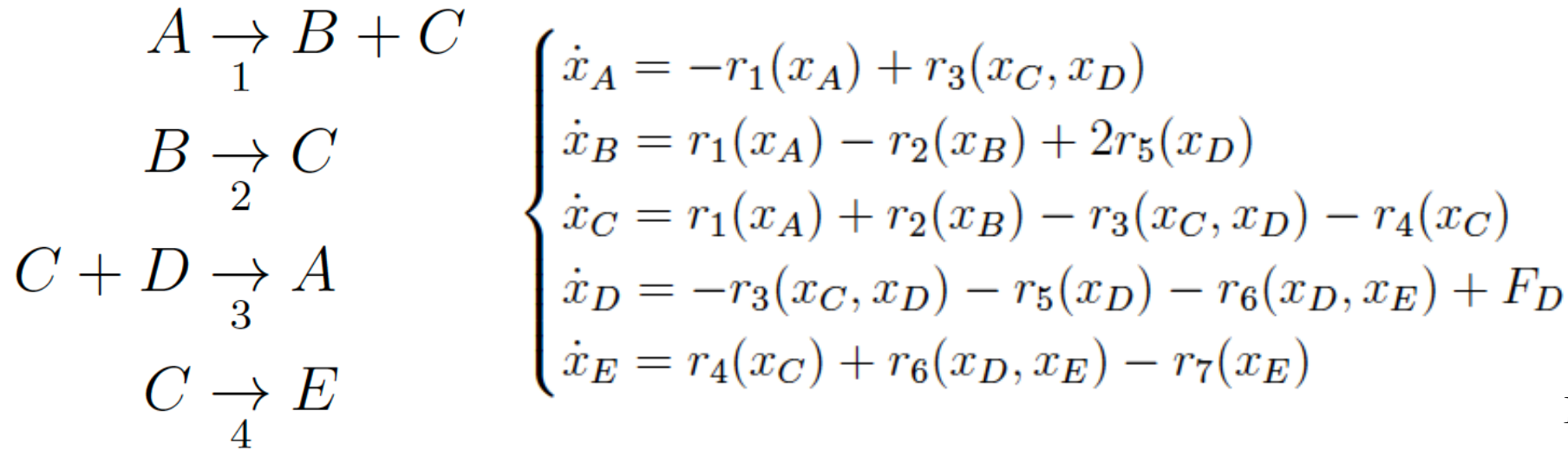


Stoichiometrically

maximal unstable positive feedback.

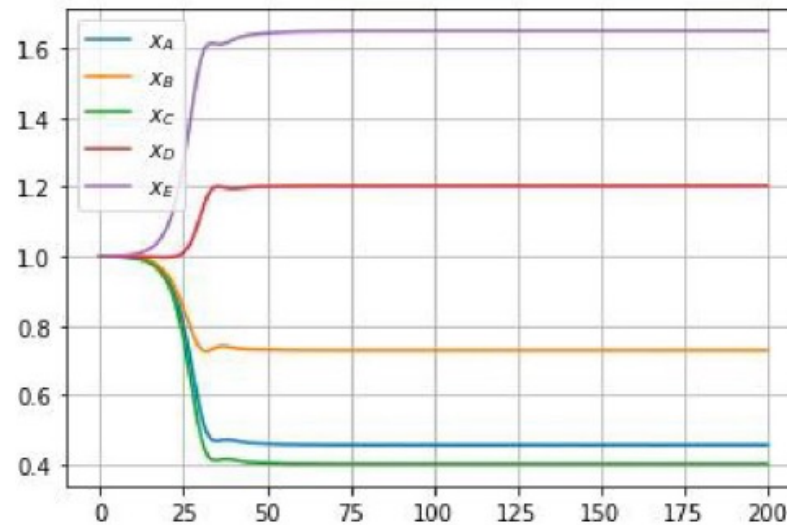
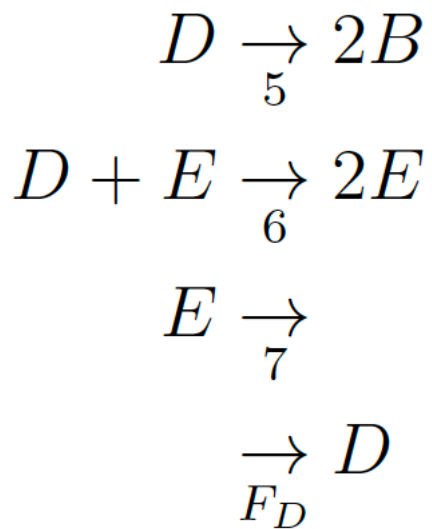
$$\det \begin{pmatrix} -1 & 0 & 1 & 0 & 0 \\ 1 & -1 & 0 & 2 & 0 \\ 1 & 1 & -1 & 0 & 0 \\ 0 & 0 & -1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} = 1$$

Example for receipt 1: Multistationarity



$$\begin{pmatrix}
 r_1(x_A) \\
 r_2(x_B) \\
 r_3(x_C, x_D) \\
 r_4(x_C) \\
 r_5(x_D) \\
 r_6(x_D, x_E) \\
 r_7(x_E) \\
 F_D
 \end{pmatrix}
 =
 \begin{pmatrix}
 4 \frac{x_A}{1+x_A} \\
 16 \frac{x_B}{1+3x_B} \\
 8 \frac{x_C}{1+x_C} \frac{x_D}{1+x_D} \\
 64 \frac{x_C}{1+15x_C} \\
 x_D \\
 32 \frac{x_D}{1+7x_D} \frac{x_E}{1+x_E} \\
 72 \frac{x_E}{1+11x_E} \\
 5
 \end{pmatrix}$$

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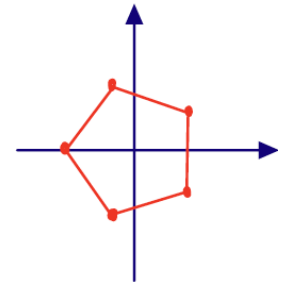
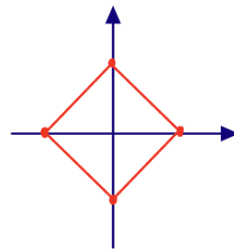
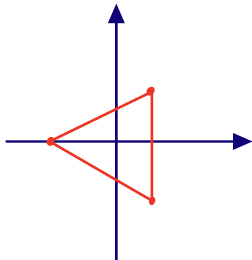
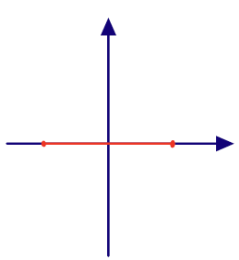


RECEIPT 2 for Oscillations

RECEIPT 2 for Oscillations

Negative-feedback cycles:

$$\begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & -1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix}$$



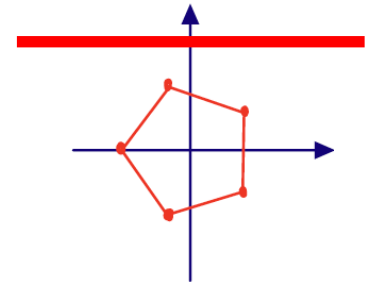
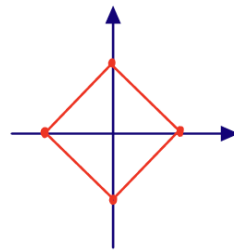
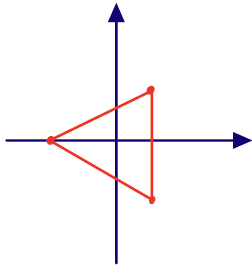
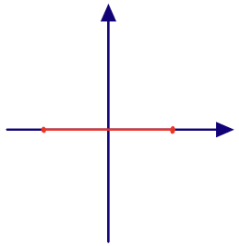
Look for even number of eigenvalues with positive real part (odd length!)

Possible network with such **cycles** (perhaps with degradations) oscillate

RECEIPT 2 for Oscillations

Negative-feedback cycles:

$$\begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & -1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix}$$



Look for even number of eigenvalues with positive real part (odd length!)

Possible network with such **cycles** (perhaps with degradations) oscillate

Example for receipt 2: Oscillations

$$2A + B \xrightarrow{1} 2A + F$$

$$2B + C \xrightarrow{2} 2B + F$$

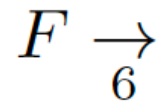
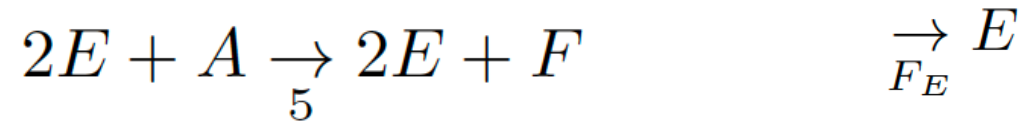
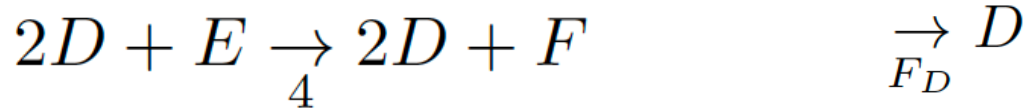
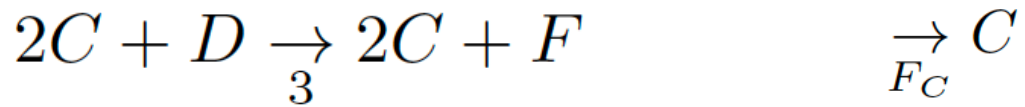
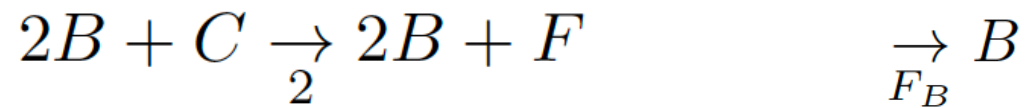
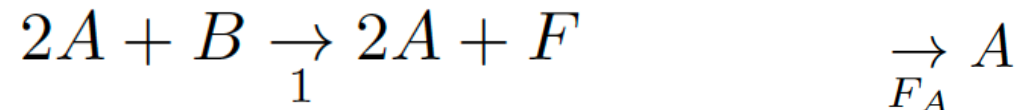
$$2C + D \xrightarrow{3} 2C + F$$

$$2D + E \xrightarrow{4} 2D + F$$

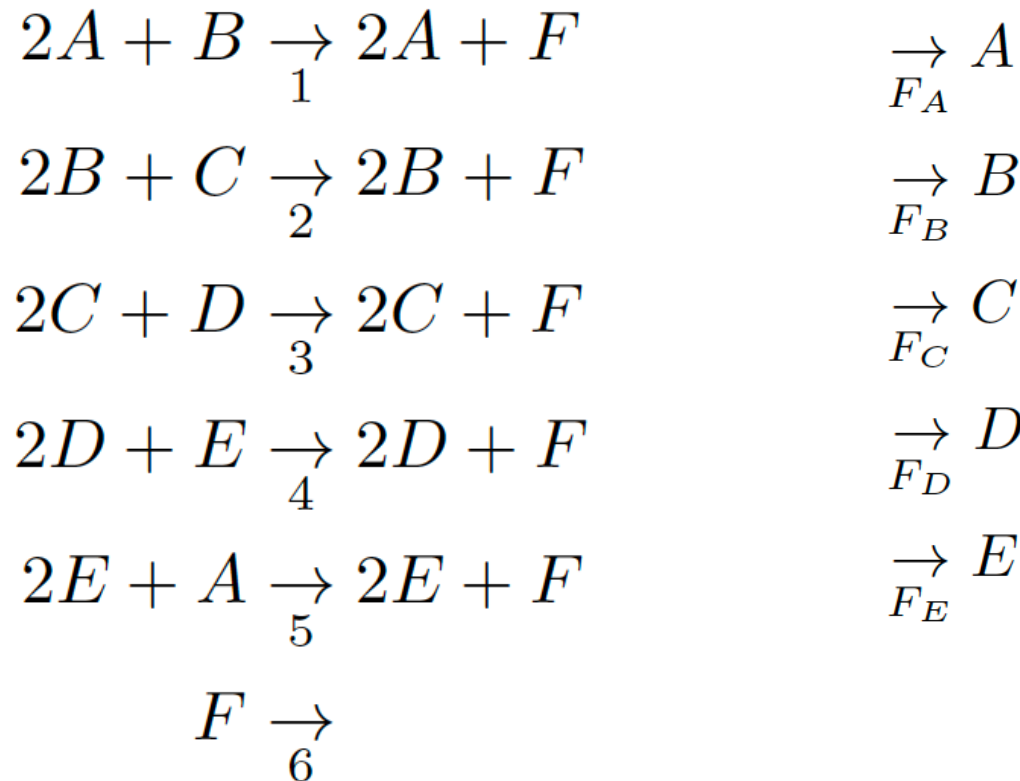
$$2E + A \xrightarrow{5} 2E + F$$

$$F \xrightarrow{6}$$

Example for receipt 2: Oscillations



Example for receipt 2: Oscillations



It contains negative feedback cycle:

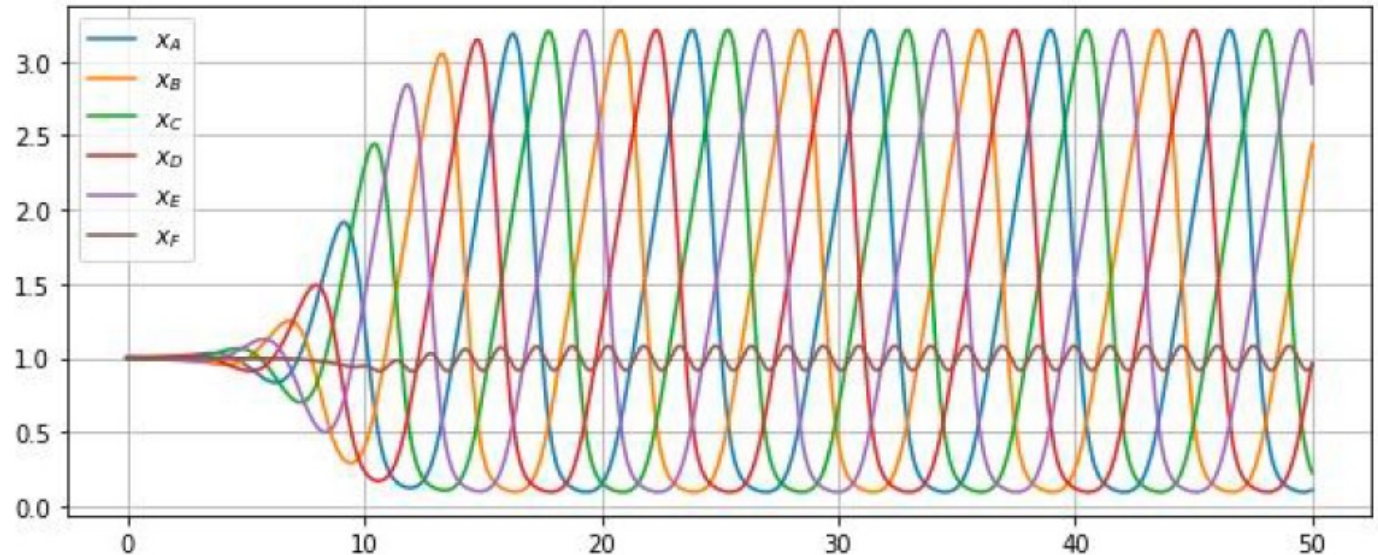
$$\begin{pmatrix} 0 & 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix}$$

REFERENCE: “Unstable cores...” (with Peter)

Example for receipt 2: Oscillations

Mass Action System:

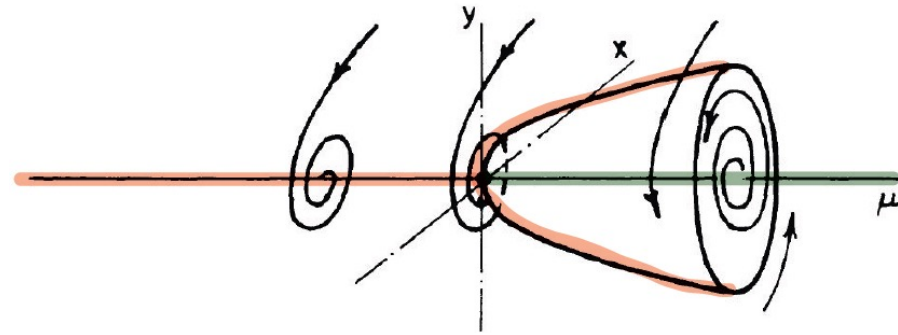
$$\begin{cases} \dot{x}_A = F_A - k_5 x_A x_E^2, \\ \dot{x}_B = F_B - k_1 x_A^2 x_B, \\ \dot{x}_C = F_C - k_2 x_B^2 x_C, \\ \dot{x}_D = F_D - k_3 x_C^2 x_D, \\ \dot{x}_E = F_E - k_4 x_D^2 x_E, \\ \dot{x}_F = k_5 x_A x_E^2 + k_1 x_A^2 x_B + k_2 x_B^2 x_C + k_3 x_C^2 x_D + k_4 x_D^2 x_E - k_6 x_F \end{cases}$$



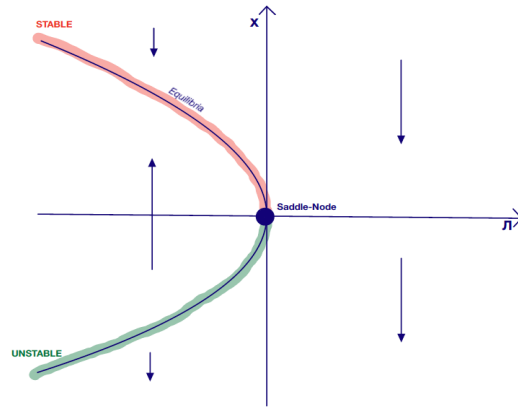
$$(k_1, k_2, k_3, k_4, k_5, k_6, F_A, F_B, F_C, F_D, F_E) = (1, 1, 1, 1, 1, 5, 1, 1, 1, 1, 1).$$

Tool: Bifurcation theory

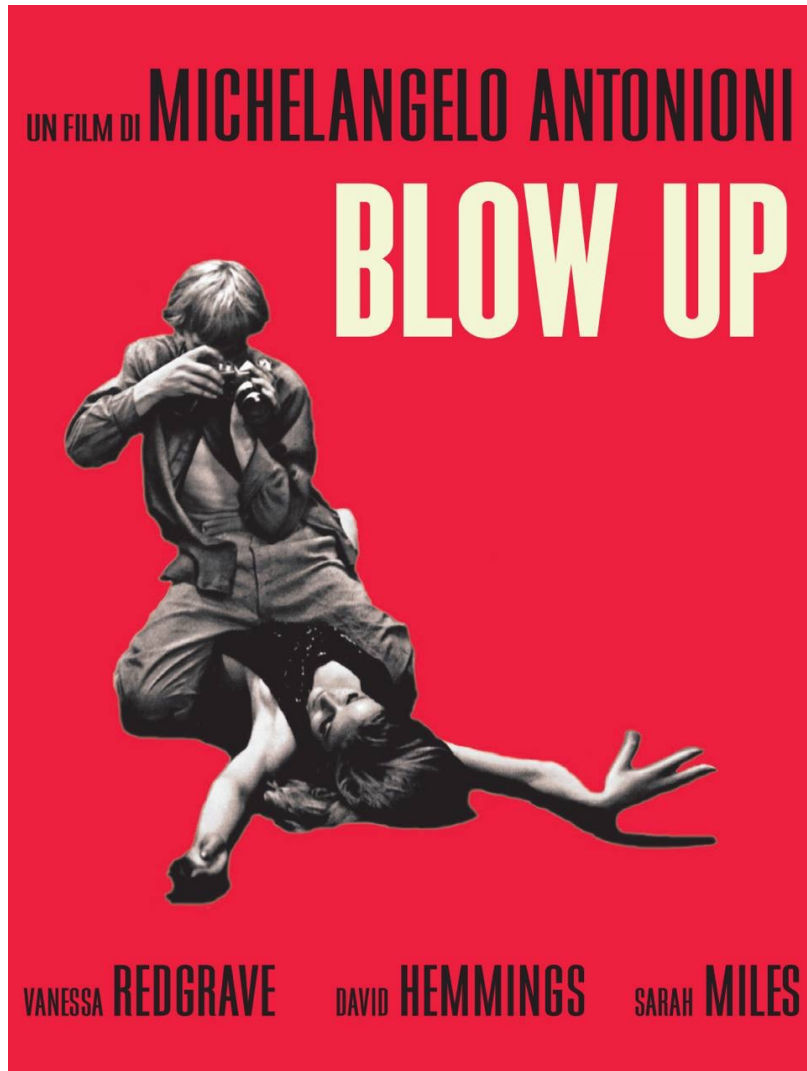
Hopf bifurcation for Oscillations



Saddle-node (at present) bifurcation for Multistationarity



How to make the small pattern dominant?



TUNE PARAMETERS!

Always possible with non-elementary kinetics
as Michaelis-Menten/Hill/Generalized Mass Action
(“parameter-rich”: see Definition with Peter)

More difficult with mass action!

GRAZIE PER L'ATTENZIONE!

