MiniCellSim a Tool for Modeling Simple Genetic and Metabolic Regulation Networks

Peter Schuster

Institut für Theoretische Chemie, Universität Wien, Austria and The Santa Fe Institute, Santa Fe, New Mexico, USA



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http://www.tbi.univie.ac.at/~pks

What is systems chemistry?

autocatalysis, template action, self-assembly, reaction networks, nonlinearity, complexity,

but also with atoms and molecules that do not occur in living matter

systems chemistry = systems biology

without genes and the Darwinian mechanism that, in principle, allows for the reconstruction of phylogenetic trees

What is systems biology?

In research on the origin of life and cellular organization the scientist has to face the unsolved problem to explain how hierarchical structures, superstructures, and complex dynamics emerge from simple (perhaps yet unknown) elements.

Perhaps we should search for simple or minimal reaction and regulator systems that can be modelled, understood, synthesized, studied experimentally, and made predictable.

In the domain of molecular genetics and systems biology it is (more or less) well known, how the individual elements (proteins, nucleic acids) work and how the regulatory switches operate, but network dynamics is not at all understood yet.

- 1. Forward and inverse problems in reaction kinetics
- 2. Reverse engineering A simple example
- 3. Genetic and metabolic networks MiniCellSim
- 4. A glimpse of regulation kinetics
- 5. How do model metabolisms evolve?

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The forward problem of chemical reaction kinetics (Level I)



The forward problem of biochemical reaction kinetics (Level I)





The forward problem of bifurcation analysis (Level II)



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$$\begin{array}{c} \text{Stock Solution } [A] = a_{0} \longrightarrow \\ \text{Reaction Mixture } [A], [X] \longrightarrow$$



Flow rate r

*
$$\xrightarrow{\mathbf{r}}$$
 A
* $\xrightarrow{\mathbf{A}}$ Kinetic differential equations:
* $\xrightarrow{\mathbf{A}}$ A
 $\frac{d[A]}{dt} = \frac{da}{dt} = r(a_0 - a) - (k_1 + k_3 x^2) a + (k_2 + k_4 x^2) x$
A $\stackrel{k_1}{\rightleftharpoons}$ X
 $\frac{d[X]}{dt} = \frac{dx}{dt} = -r x + (k_1 + k_3 x^2) a - (k_2 + k_4 x^2) x$
A +2 X $\stackrel{k_3}{\rightleftharpoons}$ 3X Steady states:
 $\overline{x}^3(k_3 + k_4) - \overline{x}^2 k_3 a_0 + \overline{x}(k_1 + k_2 + r) - k_1 a_0 = 0$
A $\stackrel{\mathbf{r}}{\rightarrow}$ 0

$$\stackrel{r}{\textbf{X}} \ \xrightarrow{} \ 0$$

$$\begin{array}{l} \mathbf{x} \xrightarrow{\mathbf{r}} \mathbf{A} \\ \mathbf{x} \xrightarrow{\mathbf{k}_{1}} \mathbf{A} \\ \stackrel{\mathbf{k}_{1}}{\rightleftharpoons} \xrightarrow{\mathbf{k}_{2}} \mathbf{X} \\ \mathbf{A} \xrightarrow{\mathbf{k}_{1}}{\rightleftharpoons} \frac{\mathbf{k}_{1}}{\mathbf{k}_{2}} \mathbf{X} \\ \mathbf{A} \xrightarrow{\mathbf{k}_{2}}{\rightleftharpoons} \mathbf{X} \\ \mathbf{A} \xrightarrow{\mathbf{k}_{2}}{\rightleftharpoons} \mathbf{X} \\ \mathbf{A} \xrightarrow{\mathbf{k}_{2}}{\rightleftharpoons} \mathbf{X} \\ \mathbf{A} \xrightarrow{\mathbf{k}_{2}}{\rightrightarrows} \mathbf{X} \\ \stackrel{\mathbf{k}_{3}}{\rightleftharpoons} \frac{\mathbf{d}[\mathbf{X}]}{\mathbf{d}\mathbf{t}} = \frac{\mathbf{d}x}{\mathbf{d}\mathbf{t}} = -r x + (k_{1} + k_{3}x^{2}) a - (k_{2} + k_{4}x^{2}) x \\ \mathbf{A} + 2 \mathbf{X} \xrightarrow{\mathbf{k}_{3}}{\rightleftharpoons} \mathbf{3} \mathbf{X} \\ \stackrel{\mathbf{r}}{\Rightarrow} \mathbf{0} \\ \mathbf{X} \xrightarrow{\mathbf{r}}{\rightarrow} \mathbf{0} \\ \mathbf{X} \xrightarrow{\mathbf{r}}{\rightarrow} \mathbf{0} \\ \begin{array}{c} \mathbf{X} \xrightarrow{\mathbf{r}}{\rightarrow} \mathbf{0} \\ \text{Polynomial discriminant of the cubic equation:} \\ \mathbf{X} \xrightarrow{\mathbf{r}}{\rightarrow} \mathbf{0} \\ \begin{array}{c} \mathbf{X} \xrightarrow{\mathbf{r}}{\rightarrow} \mathbf{0} \\ \mathbf{X} \xrightarrow{\mathbf{r}}{\rightarrow} \mathbf{0} \\ \mathbf{X} \xrightarrow{\mathbf{r}}{\rightarrow} \mathbf{0} \end{array}$$

r
*
$$\rightarrow$$
 AKinetic differential equations:* \rightarrow A $\frac{d[A]}{dt} = \frac{da}{dt} = r(a_0 - a) - (k_1 + k_3 x^2) a + (k_2 + k_4 x^2) x$ A $\frac{k_1}{k_2}$ X $\frac{d[X]}{dt} = \frac{dx}{dt} = -r x + (k_1 + k_3 x^2) a - (k_2 + k_4 x^2) x$ A +2 X $\frac{k_3}{k_4}$ 3XSteady states: $\overline{x^3}(k_3 + k_4) - \overline{x}^2 k_3 a_0 + \overline{x}(k_1 + k_2 + r) - k_1 a_0 = 0$ $k_1 = k_2 = \alpha, k_3 = k_4 = 1$: $2\overline{x^3} - \overline{x^2} a_0 + \overline{x}(r + 2\alpha) - \alpha a_0 = 0$ A \overrightarrow{r} 0 $k_1 = k_2 = \alpha, k_3 = k_4 = 1$: $2\overline{x}^3 - \overline{x}^2 a_0 + \overline{x}(r + 2\alpha) - \alpha a_0 = 0$ Polynomial discriminant of the cubic equation: $216 D = r^3 + r^2 (6\alpha - \frac{a_0^2}{8}) + r(12\alpha^2 - 5\alpha a_0^2) + 8\alpha^3 + 4\alpha^2 a_0^2 + \frac{\alpha a_0^4}{2} = 0$ D < 0: 3 roots r_1, r_2, and r_3, 2 are positive $\Rightarrow \Delta \mathbf{r} = r_1 - r_2$



Range of hysteresis as a function of the parameters a_0 and α

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Sketch of a genetic and metabolic network



Proposal of a new name:

Genetic and metabolic network



The elements of the simulation tool MiniCellSim

SBML: Bioinformatics **19**:524-531, 2003; *CVODE: Computers in Physics* **10**:138-143, 1996



The regulatory logic of MiniCellSym



The chemical reaction dynamics of MiniCellSym



The model regulatory gene in MiniCellSim



The model structural gene in MiniCellSim

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Active states of gene regulation





Inactive states of gene regulation



Cross-regulation of two genes

Activation:
$$F_i(p_j) = \frac{p_j^n}{K + p_j^n}$$

Repression: $F_i(p_j) = \frac{K}{K + p_j^n}$
 $i, j = 1, 2$

Gene regulatory binding functions

$$[G_{1}] = [G_{2}] = g_{0} = \text{const.} \qquad \frac{dq_{1}}{dt} = k_{1}^{Q} F$$

$$[Q_{1}] = q_{1}, [Q_{2}] = q_{2}, \qquad \frac{dq_{2}}{dt} = k_{1}^{Q} F$$

$$[P_{1}] = p_{1}, [P_{2}] = p_{2} \qquad \frac{dq_{2}}{dt} = k_{1}^{Q} F$$

Activation:
$$F_i(p_j) = \frac{p_j^n}{K + p_j^n}$$

Repression: $F_i(p_j) = \frac{K}{K + p_j^n}$
 $i, j = 1, 2$
 $\overline{dt} = k_2 T_2(1)$
 $\frac{dp_1}{dt} = k_1^p q_1 - \frac{dp_2}{dt} = k_2^p q_2 - \frac{dp_2}{dt}$

$$\frac{dq_1}{dt} = k_1^Q F_1(p_2) - d_1^Q q_1$$
$$\frac{dq_2}{dt} = k_2^Q F_2(p_1) - d_2^Q q_2$$
$$\frac{dp_1}{dt} = k_1^P q_1 - d_2^P p_1$$
$$\frac{dp_2}{dt} = k_2^P q_2 - d_2^P p_2$$

Stationary points: $\overline{p}_1 - \mathcal{P}_1 F_1(\mathcal{P}_2 F_2(\overline{p}_1)) = 0, \ \overline{p}_2 = \mathcal{P}_2 F_2(\overline{p}_1)$

$$\mathcal{G}_{1} = \frac{k_{1}^{Q}k_{1}^{P}}{d_{1}^{Q}d_{1}^{P}}, \, \mathcal{G}_{2} = \frac{k_{2}^{Q}k_{2}^{P}}{d_{2}^{Q}d_{2}^{P}}$$

Qualitative analysis of cross-regulation of two genes

$$(\varepsilon + d_1^{Q})(\varepsilon + d_2^{Q})(\varepsilon + d_1^{P})(\varepsilon + d_2^{P}) + D = 0$$

Eigenvalues of the Jacobian of the cross-regulatory two gene system

$$D = -k_1^{\mathrm{Q}} k_2^{\mathrm{Q}} k_1^{\mathrm{P}} k_2^{\mathrm{P}} \Gamma(\overline{p}_1, \overline{p}_2)$$



 $(\varepsilon + d_1^{\mathrm{Q}})(\varepsilon + d_2^{\mathrm{Q}})(\varepsilon + d_1^{\mathrm{P}})(\varepsilon + d_2^{\mathrm{P}}) + D = 0$

Eigenvalues of the Jacobian of the cross-regulatory two gene system

 $D = -k_1^{\mathsf{Q}} k_2^{\mathsf{Q}} k_1^{\mathsf{P}} k_2^{\mathsf{P}} \Gamma(\overline{p}_1, \overline{p}_2)$



$$D_{\text{OneD}} = -d_1^{\text{Q}} d_2^{\text{Q}} d_1^{\text{P}} d_2^{\text{P}}$$

$$D_{\text{Hopf}} = \frac{(d_1^{\text{Q}} + d_2^{\text{Q}})(d_1^{\text{Q}} + d_1^{\text{P}})(d_1^{\text{Q}} + d_2^{\text{P}})(d_2^{\text{Q}} + d_1^{\text{P}})(d_2^{\text{Q}} + d_2^{\text{P}})(d_1^{\text{P}} + d_2^{\text{P}})}{(d_1^{\text{Q}} + d_2^{\text{Q}} + d_1^{\text{P}} + d_2^{\text{P}})^2}$$



Regulatory dynamics at $D \le 0$, act.-act., n=2



Regulatory dynamics at $D \ge 0$, act.-rep., n=3





Regulatory dynamics at $D < D_{Hopf}$, act.-repr., n=3



 $q_1(t), p_1(t)$

Regulatory dynamics at $D > D_{Hopf}$, act.-repr., n=3



Regulatory dynamics at $D \le 0$, rep.-rep., n=2

Hill coefficient: n	ActAct.	ActRep.	RepRep.
1	S , E	S	S
2	E , B(E,P)	S	$S, B(P_1,P_2)$
3	E , B(E,P)	S,O	$S, B(P_1,P_2)$
4	E , B(E,P)	S,O	$S, B(P_1,P_2)$

Activation:
$$F_i(p_j) = \frac{p_j^n}{K + p_j^n}$$

Repression: $F_i(p_j) = \frac{K}{K + p_j^n}$
Intermediate: $F_i(p_j) = \frac{p_j^m}{\kappa_1 + \kappa_2 p_j + \kappa_3 p_j^2 + \ldots + p_j^n}$

 $i, j = 1, 2; \quad 1 \le m \le n - 1$



Regulatory dynamics, int.-act., m=2, n=4





Regulatory dynamics, rep.-int., m=2, n=4



An example analyzed and simulated by MiniCellSim

The repressilator: M.B. Ellowitz, S. Leibler. A synthetic oscillatory network of transcriptional regulators. *Nature* **403**:335-338, 2002



Proteins





The repressilator limit cycle

Proteins

mRNAs



The repressilator heteroclinic orbit

Proteins

mRNAs



The repressilator heteroclinic orbit (logarithmic time scale)



The repressilator limit cycle



The repressilator heteroclinic orbit

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A genabolic network formed from a genotype of n = 200 nucleotides



Evolutionary time scale [generations]: 0000 initial network

Intracellular time scale

Evolution of a genabolic network:

Initial genome: random sequence of length **n = 200**, **AUGC** alphabet

Gene length: n = 25

Simulation with mutation rate: **p = 0.01**

Evolutionary time unit >> intracellular time unit



Number of genes: total / structural genes regulatory genes

Genes 12/06 - Time 0000

Evolution of a genabolic network:

Initial genome: random sequence of length **n = 200**, **AUGC** alphabet

Gene length: **n = 25**

Simulation with mutation rate: **p** = 0.01

Evolutionary time unit >> intracellular time unit

Recorded events:

- (i) Loss of a gene through corruption of the start signal "**TA**" (analogue of the "**TATA** Box"),
- (ii) creation of a gene,
- (iii) change in the edges through mutation-induced changes in the affinities of translation products to the binding sites, and
- (iv) change in the class of genes (tf \Leftrightarrow sp).



Statistics of one thousand generations

Total number of genes:	11.67 ± 2.69
Regulatory genes:	5.97 ± 2.22
Structural genes:	5.70 ± 2.17

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