of Graph Relations

Yangjing Long

#### Outline

Defini

Fundame<mark>nta</mark>l Prob.

Complexity

Future Works

## Computational Complexity of Graph Relations

## Yangjing Long

Max Planck Institute for Math. in the Sci.

Feb. 16, 2012 Winerseminar, Bled

## Outline

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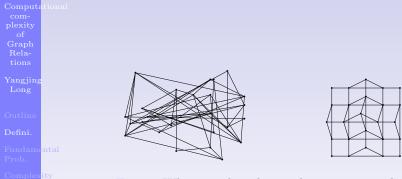
## **1** Background and Definitions

2 Fundamental Problem and Properties

## 3 Computational Complexity



## How to relate two graphs/networks?



Future Works Figure: What are the relations between networks?

## Model in biology

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## • Domain interaction graph.



• **Relation**: containing relation=

 $\{d_2, d_3 \in p_1; d_4 \in p_2; d_1, d_3 \in p_3; d_1 \in p_4\}$ 

## Model in biology

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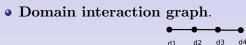
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• **Relation**: containing relation=

 $\{d_2, d_3 \in p_1; d_4 \in p_2; d_1, d_3 \in p_3; d_1 \in p_4\}$ 

• We define a **protein interaction graph**, the vertex set are proteins, two proteins have interaction if there are two interacted domains which belong to them respectively.



Figure: Protein Interaction Network

## From Biology to Mathematics

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Future Works Firstly, we generalize the containing relation to a binary relation.

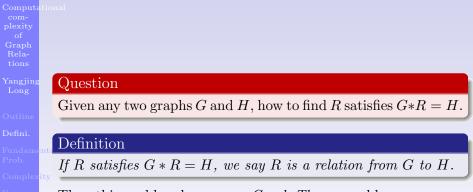
## Definition

The (binary) relation R between two sets A and B is a subset of  $A \times B$ .

## Definition

Let  $G = (V_G, E_G)$  be a simple graph with loops allowed,  $R \subset V_G \times B$  be a binary relation, G \* R is defined as a graph with vertex set B (B is given by R). For  $u, v \in B$ ,  $u \sim v$  if and only if there exist  $(x, y) \in E_G$ ,  $(x, u), (y, v) \in R$ .

## Our fundamental problem



Then this problem becomes a *Graph Theory* problem.

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Future Works • A graph homomorphism f from a graph  $G \to H$  is a **mapping**  $f: V_G \to V_H$  such that whenever (u, v) is an edge of G, we have (f(u), f(v)) is an edge of H.

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- A graph homomorphism f from a graph  $G \to H$  is a mapping  $f: V_G \to V_H$  such that whenever (u, v) is an edge of G, we have (f(u), f(v)) is an edge of H.
- If the mapping  $f: V_G \to V_H$  and  $f^{\#}: E_G \to E_H$  are both surjective, we call it *surjective homomorphism*.

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- A graph Multihomomorphism  $G \to_m H$  is a mapping  $\varphi$ :  $V_G \to 2^{V_H} / \{\emptyset\}$  (i.e., associating a nonempty subset of vertices of H with every vertex of G) such that whenever  $u_1, u_2$ is an edge of G, we have  $(v_1, v_2)$  is an edge of H for every  $v_1 \in \varphi(u_1)$  and every  $v_2 \in \varphi(u_2)$ .

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- If we consider G \* R = H with **full domain**, i.e., every vertex in G has at least an image in H, then R can be seen as a surjective multihomomorphism.

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## • homomorphism $\iff$ multihomomorphism

A graph homomorphism f can be seen as a multihomomorphism (a vertex u is assigned the one-element set  $\{f(u)\}$ ).

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## $\bullet \ homomorphism \Longleftrightarrow multihomomorphism \\$

A graph homomorphism f can be seen as a multihomomorphism (a vertex u is assigned the one-element set  $\{f(u)\}$ ). Observely, if there exists a multihomomorphism, then these is a homomorphism induced from multihomomorphism, by retaining one vertex from the image of each vertex and removing the others.

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• Multihomomorphism is a generalization of homomorphism. Graph relation is a generalization of surjective graph homomorphism.

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- Multihomomorphism is a generalization of homomorphism. Graph relation is a generalization of surjective graph homomorphism.
- If G \* R = H, then there exist a homomorphism from G to H, but NOT vice versa.

## Composition and Decomposition

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## Proposition

Lemma

$$(G * R) * S = G * (R \circ S).$$

 $R = R_D \circ R_C, (G * R_D) * R_C = H.$ 

$$G \xrightarrow{R} H$$

$$R_D \xrightarrow{R_C} R_C$$

For any R satisfing G \* R = H, there exists  $R_D, R_C$  such that

## Our fundamental problem

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## Question

Given any two graphs G and H, how to find R satisfies G \* R = H.

The existence of the relations is non-trivial:

• it could have a relation





Figure: there exists a relation of G to H

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## Question

Given any two graphs G and H, how to find R satisfies G \* R = H.

The existence of the relations is non-trivial:

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Figure: there exists a relation of G to H

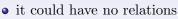




Figure: no relations of G to H

## Diameter decrease

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The *distance* between two vertices in a graph is the number of edges in a shortest path connecting them. The *diameter* of a graph is the greatest distance between any pair of vertices.

## Proposition

If G \* R = H, then  $max\{diam(G), 2\} \ge diam(H)$ .

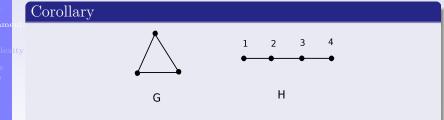


Figure: 2 < diam(H) = 3, so no relations of G to H

## Chromatic number increase

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Future Works A coloring of a graph is a labelling of the graph's vertices with colors such that no two vertices sharing the same edge have the same color. The smallest number of colors needed to color a graph G is called its *chromatic number*,  $\chi(G)$ .

## Proposition

Suppose G and H are simple graphs. If G \* R = H, then  $\chi(G) \leq \chi(H)$ .

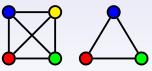


Figure:  $\chi(K_4) > \chi(K_3)$ , so no relation from  $K_4$  to  $K_3$ .

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### Definition

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## Two graphs G and H are strongly relationally equivalent, G ~ H, if G \* R = H and H \* R<sup>+</sup> = G, where R<sup>+</sup> is the transpose of R, i.e., $(u, x) \in R^+$ if and only if $(x, u) \in R$ .

### Lemma

Strongly relational equivalence is an equivalence relation on graphs.

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## Definition

Two graphs G and H are strongly relationally equivalent, G ~ H, if G \* R = H and H \* R<sup>+</sup> = G, where R<sup>+</sup> is the transpose of R, i.e.,  $(u, x) \in R^+$  if and only if  $(x, u) \in R$ .

### Lemma

Strongly relational equivalence is an equivalence relation on graphs.

### Question

How to find the simpliest(smallest) represented elments?

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## Definition

Denote thin graph of graph G by  $G_{thin}$ , which is obtained from G by contracting the vertices with the same neighborhoods together.

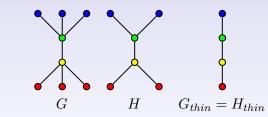


Figure: Non-isomorphic graphs G and H with isomorphic thin graphs.

### Theorem

Two graph are strongly relationally equivalent iff their thin graphs are the same.

In other words, *thin graphs* ares the represented elements of <u>Fundamenta</u> strongly relational equivalent classes.

### Observation

We could simplify the equation G \* R = H to  $G_{thin} * R = H_{thin}$ .

## Computation Let $\mathcal{H}$ be a fixed graph.

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## Definition

The homomorphism problem  $HOM(\mathcal{H})$  takes as input some finite  $\mathcal{G}$  and asks whether there is a homomorphism from  $\mathcal{G}$ .

## Definition

The surjective homomorphism problem  $\text{Sur-HOM}(\mathcal{H})$  asks whether or not an input graph  $\mathcal{G}$  admits a surjective homomorphism to  $\mathcal{H}$ .

## Definition

The relation problem  $\operatorname{ReL}(\mathcal{H})$  asks whether or not an input graph  $\mathcal{G}$  admits a relation to  $\mathcal{H}$ .

Clearly two relationally equivalent graphs result in the same relation problem.

## Polynomial Equivalence to SUR-HOM $(\mathcal{H})$

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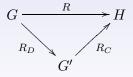
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## This is an observation of Prof. Jarik Nešetřil.

From decomposition lemma, we know G \* R = H iff there is a graph  $G' = G * R_D$  which has a (full) homomorphism to Gand has a surjective homomorphism to H. For a fixed H, given a graph G, we duplicate every vertex of G at most |H| times, there are polynomially many G'. Thus, the H relation problem is polynomial-time equivalent to SUR-HOM( $\mathcal{H}$ ).



## Polynomial Equivalence to SUR-HOM $(\mathcal{H})$

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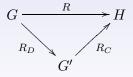
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## SUR-HOM( $\mathcal{H}$ ) is still *OPEN*.

• If H is  $K_2$ , there exists relation R such that G \* R = H iff G is a bipartite graph. So in this case the problem is polynomial.

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Future Works • If H is  $K_3$ , the problem is polynomial equivalent with 3colourable problem, which is NP-complete.

## $\operatorname{Sur-Hom}(\mathcal{H}) \operatorname{VS} \operatorname{Hom}(\mathcal{H})$

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## This is an observation of Jan Hubička.

## Proposition

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Future Works Existence of homomorphism from G to H is the same as existence of surjective homomorphisms from G + H to H.

So SUR-HOM( $\mathcal{H}$ ) is obviously hard for all graphs where homomorphisms are *hard*.

Definition

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Complexity Future Two graphs G and H are (weakly) relationally equivalent,  $G \sim H$ , if there are relations R and S such that G \* R = H and H \* S = G.

Strong relational equivalence implies weak relational equivalence. To see this, simply note the definition of the weak from is obtained from the strong one by setting  $S = R^T$ .

Definition

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## Observation

Weak and strong relational equivalence are not the same.

This is an observation of Jan Hubička

Observation

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## This is an observation of Jan Hubička

# Outline Definit Example Find among the Prob. Image: Complexity of the problem of the proble

Weak and strong relational equivalence are not the same.

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Represented elements of weakly relational equivalence classes are not thin graphs, and more precise than thin graphs.

## Question

How to find the represented element of weakly relational equivalence classes? Complexity

## Special thanks to

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Thank for your attention Christoph Peter Jürgen Honza Frank and Tina