

Instituto de Física Universidade de São Paulo

Axelrod's discrete model for the dissemination of Cultures: from dynamics on a network to its landscape

Bruno Pace

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- q = 2, q = 3 and $q \ge 4$.

Conclusion

Motivation and Model's Description

- Culture was defined by Axelrod, in a simple fashion, as the set of people's characteristics subject to other individual's influence.
- The cultural state of an individual is therefore a multidimensional and discrete vector.
- The cultural vetor consists of F cultural features, each of which can express one of q possible traits:

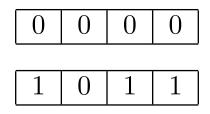
- $\sigma_i^f \in \{0, 1, 2, \dots, q-1\}$
- These two parametres, F and q, are related to cultural diversity, and the dynamics depend on their choice.

Comparing Vectors

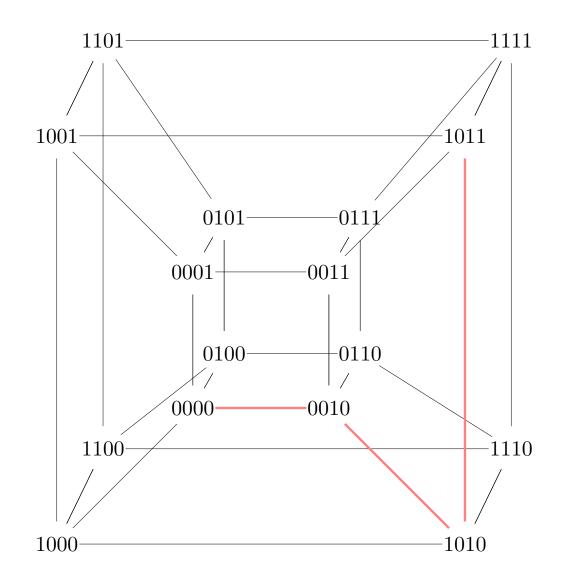
- "The transfer of ideas occurs most frequently between individuals [...] who are similar in certain attributes such as beliefs, education, social status, and the like"
- Hamming distance: $d_{\vec{\sigma_i},\vec{\sigma_j}} = F \sum_{f=1}^F \delta_{\sigma_i^f,\sigma_j^f}$

• Similarity:
$$\omega_{ij} = \frac{1}{F} \sum_{f=1}^{F} \delta_{\sigma_i^f, \sigma_j^f}$$

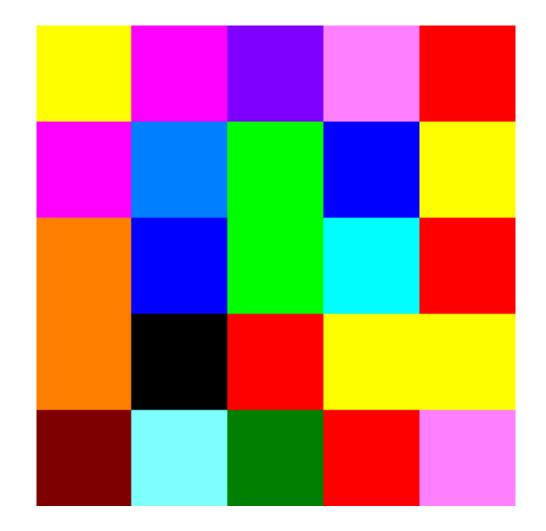
• Example: F = 4, q = 2



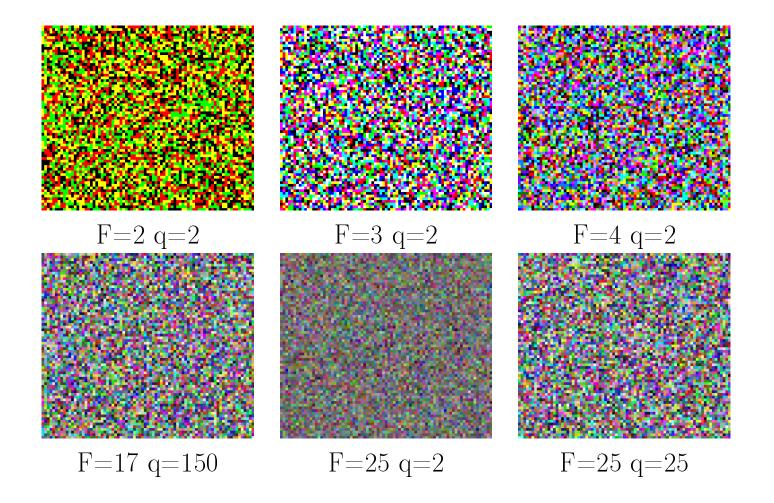
• Example of the cultural space, with F = 4 and q = 2:



The node representation: Connection topologies: regular square lattice (periodic boundary conditions)



Initial conditions: Uniform distribution L = 80



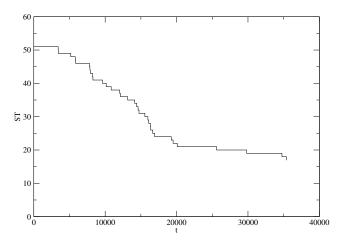
Dynamics

- Asynchronous and stochastic model
- Iteration of the following steps:
 - **Step 1**: Randomly choose one active site *i* and one of its neighbours $j \in \nu_i$, where ν_i is the neighbourhood of site *i*.
 - **Step 2**: With a probability equal to their similarity, there is an interaction. The interaction consists of randomly selecting an f such that $\sigma_i^f \neq \sigma_j^f$ (if there is), and making site j adopt σ_i^f .
- A site i is active if at least one of its neighbours j is in a state such that $0 < \omega_{ij} < 1$
- This is not an 'energy-driven' process.
- Markov chain: The configuration space can be represented by a directed graph, where nodes are configurations and the directed edges are possible transitions associated with their probabilities.
- Time evolution is a random walk on this graph.

Transient behaviour

- In every interaction one cultural trait is discarded, eventually becoming extinct
- One possible Lyapunov function is given by the counting of Surviving Traits in every time step

$$ST = qF - \sum_{f=1}^{F} \sum_{t=0}^{q-1} [\delta_{0,\sum_{i=1}^{N} \delta_{t,\sigma_{i}}^{f}}]$$



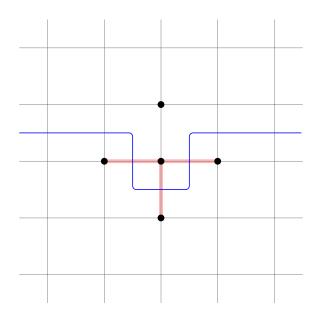
Time series of the Lyapunov Function ST L = 60, F = 17 and q = 3.

The Model with Surface Tension

Model's description and motivation:

• A subtle difference is introduced:

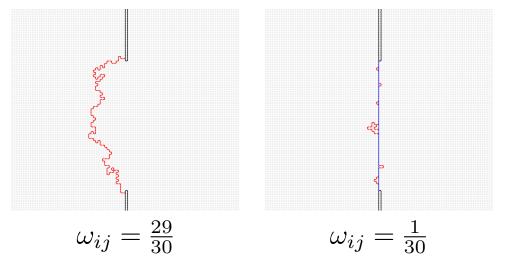
Step 1: Randomly choose one active site *i* and one of its neighbours *j* such that $0 < \omega_{ij} < 1$. **Step 2**: With a probability equal to their similarity, there is an interaction. The interaction consists of randomly selecting an *f* such that $\sigma_i^f \neq \sigma_j^f$ and making site *j* adopt σ_i^f .



The Model with Surface Tension

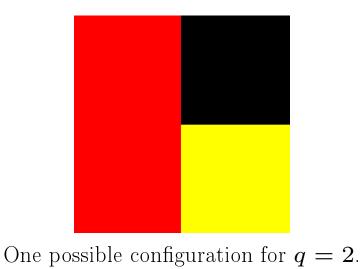
Consequences:

- Cultural cohesion and spatial localization
- Cultural borders and membranes cultural exchange and multicultural regions
- Simple or composed membranes adhesion tendency
- Metastability
- This is achieved without changing topologically the configuration space.

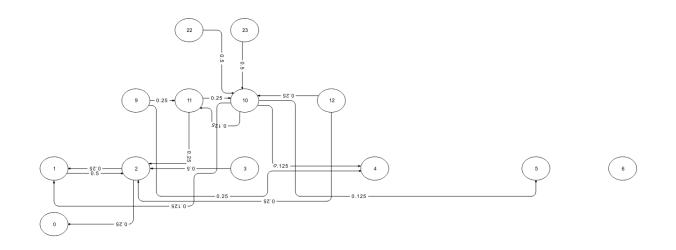


Simplest case: L = 2, F = 2

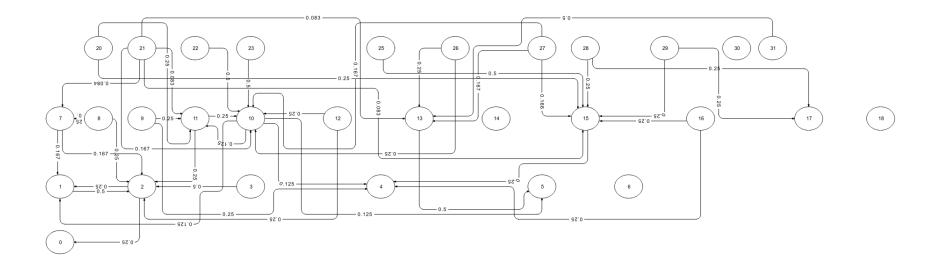
- Number of nodes in the configuration space: q^8
- Lyapunov function associated: landscape
- Collapsing nodes by symmetry drastic reduction of landscape size.



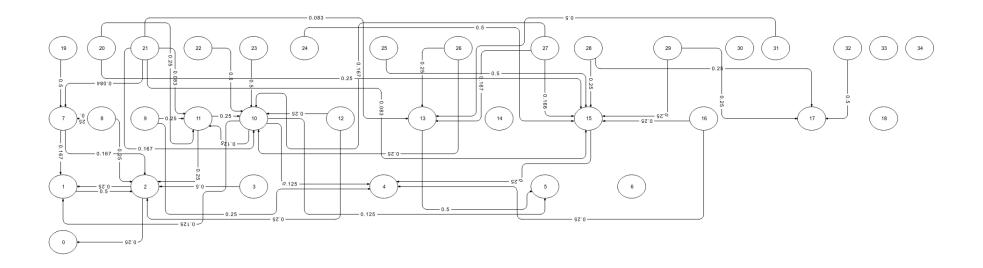
Simplest case: L = 2, F = 2, q = 2 (13 nodes)



Simplest case: L = 2, F = 2, q = 3 (30 nodes)



Simplest case: $L = 2, F = 2, q \ge 4$ (35 nodes)



- Dynamics equivalent to random walk based on the weights.
- Distributing probabilities, time evolution and stationary distribution are obtained.
- The surface tension was introduced without changing the topology, only the weights.

Conclusion

- Discrete dynamic model on a network, discrete configuration space.
- Subtle modification of Axelrod's Model the topology of the configuration space is not altered, but the dynamics are.
- Landscape topology and transition probabilities drive dynamics.
- Distribution of weights create different attractor structures throughout landscape (metastability).

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