

TBA@TBI WinterSeminar

... as advertised on the event website

Yann Ponty

+ Bertrand Marchand*, Sebastian Will, Sarah Berkemer and Laurent Bulteau

AMIBio Team
CNRS & LIX, Institut Polytechnique de Paris

Automated Design of Dynamic Programming Algorithms

Another step towards the elusive perfect algorithm for folding RNAs with tertiary motifs

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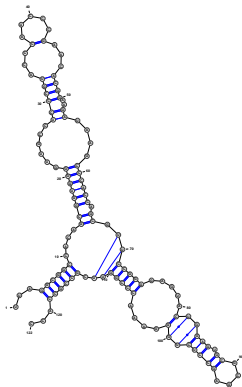
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RNA structure(s)

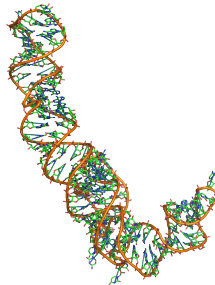
RNA = Linear Polymer = Nucleotides sequence $w \in \{A, C, G, U\}^*$

```
UUAGGCGGCCACAGC
GGUGGGGUUGCCUCC
CGUACCCAUCCCGAA
CACGGAAGAUAAAGCC
CACCAGCGUCCGGG
GAGUACUGGAGUGCG
CGAGCCUCUGGGAAA
CCCGGUUCGCCGCCA
CC
```

Primary struct.
aka sequence

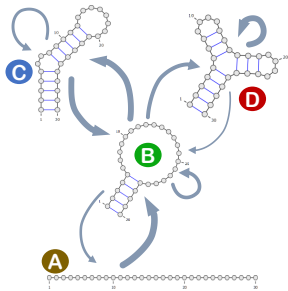


Secondary struct.

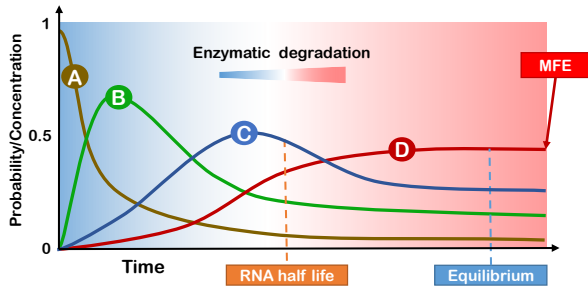


Tertiary (\approx 3D) struct.
5s rRNA (PDB ID: 1K73:B)

Physics/chemistry paradigms in RNA structural bioinformatics



A – Kinetic Landscape
Continuous-time Markov chain

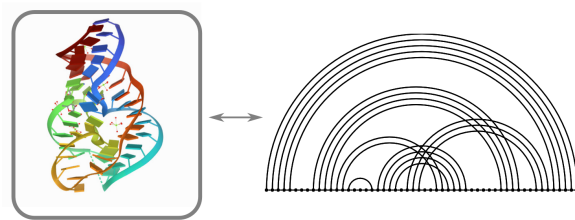
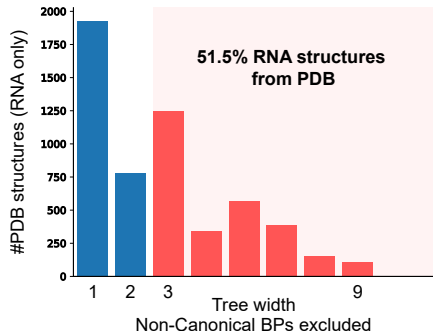


B – Evolution of concentrations

Given **free-energy** E at Boltzmann equilibrium $\mathbb{P}(S | w) \propto e^{-\Delta G(w,S)/RT}$

- ▶ **Minimum Free-Energy (MFE)**: Functional structure = Most stable/probable
- ▶ **Partition function**: Equilibrium properties of Boltzmann ensemble
- ▶ **Kinetics**: Finite-time evolution of concentrations/probabilities

Why pseudoknots?



Twister ribozyme (PDB ID: 3OJI)

Pseudoknots are **highly prevalent** among non-coding RNAs:

- ▶ **48.5% RNA structures from PDB** feature pseudoknots
- ▶ **565 RFAM families** have pseudoknotted consensus structures

The CS/nerdy side of MFE prediction (with pseudoknots)

- ▶ **Pseudoknot-free MFE** solved in $O(n^3)$ time for finite energy models

Current best: $O(n^{2.87})$ for BP-based models

[Bringmann, Grandoni, Saha, & Williams 2016]

Lower bounds: SETH $\rightarrow O(n^2)$, k -clique $\rightarrow O(n^\omega)$, $\omega < 2.374$

[Abboud, Backurs & Williams 2015]

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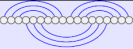

[Bringmann, Grandoni, Saha, & Williams 2016]

Lower bounds: SETH $\rightarrow O(n^2)$, k -clique $\rightarrow O(n^\omega)$, $\omega < 2.374$

[Abboud, Backurs & Williams 2015]

- ▶ **With pseudoknots** \rightarrow NP-hard for **any realistic energy model**

[Lyngsø & Pedersen 2000; Akutsu & Uemura 2000; Sheikh, Backofen & Ponty 2012]

		Base-pairs	Stacking-Pairs	Nearest-Neighbor
	Comp.	P [Nussinov 80]	P [leong 03]	P [Zuker 81]
Non-crossing	Approx.	–	–	–
	Comp.	???	NP-Hard [leong 03]	NP-Hard [leong 03]
Planar	Approx.	2-approx. \approx [leong 03]	2-approx. [leong 03]	???
	Comp.	P [Tabaska 98]	NP-Hard [Lyngsø 04] (any* Δ model)	NP-Hard [Lyngsø 00, Akutsu 00]
General	Approx.	–	ϵ -approx. $\in O(n^{4^{1/\epsilon}})$ [Lyngsø 04] 1/5 (any Δ model)	APX-Hard

History of RNA folding with PK (+ Interactions)

Tool	Reference	space	time	restriction
Pknots-RE	[Rivas and Eddy, 1999]	$O(n^4)$	$O(n^6)$	“one-hole structures”
NUPACK	[Dirks and Pierce, 2003]	$O(n^4)$	$O(n^5)$	“2 interleaved helices”
gfold	[Reidys et al., 2011]	$O(n^4)$	$O(n^6)$	genus ≤ 1
CCJ	[Chen et al., 2009]	$O(n^4)$	$O(n^5)$	“3 groups of bands”
Knotty	[Jabbari et al., 2018]	$O(n^3 + Z)$	$O(n^5)$	“CCJ-type + optims”
Pknots-RG	[Reeder and Giegerich, 2004]	$O(n^2)$	$O(n^4)$	“simple recursive PK”

- ▶ Manual design using Dynamic Programming (DP)
- ▶ Grammar-based frameworks [Giegerich & friends, Hoehner zu Siederdisen& Stadler]
- ▶ Topology-inspired (Genus \rightarrow Fatgraphs) [Bon/Orland/Vernizzi, Reidys/Nebel/Stadler]



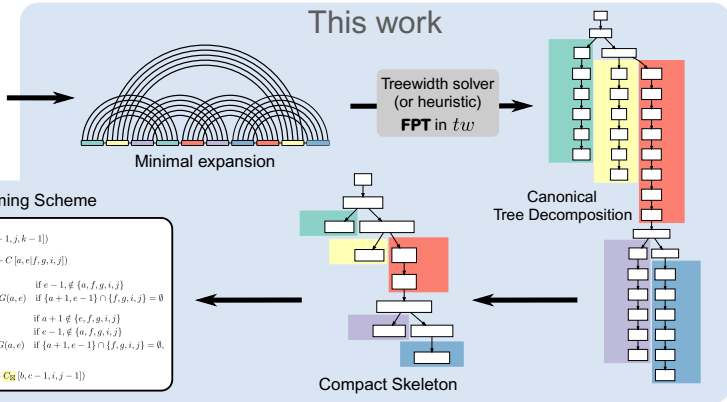
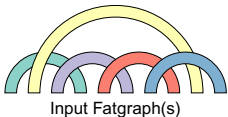
Our goal: To rationalize/automate the design of *conjunctive* DP schemes

Workflow

PK pattern(s) of interest (e.g. 3D models)



Abstracted as ↓



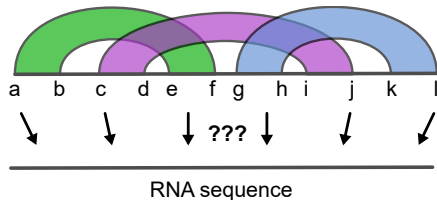
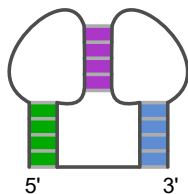
$$\begin{aligned}
 A &= \min_{a,g,h,j,k} (B[a,g,h,j] + C_{\text{ax}}[g,h-1,j,k-1]) \\
 B[a,g,h,j] &= \min_{e,f,i} (C_{\text{ax}}[e,f-1,h,i-1] + C[a,e|f,g,i,j]) \\
 C_{\text{ax}}[a,e|f,g,i,j] &= \min \begin{cases} C'[a,e-1|f,g,i,j], & \text{if } e-1 \notin \{a,f,g,i,j\} \\ C[a+1,e-1|f,g,i,j] + \Delta G(a,e) & \text{if } \{a+1,e-1\} \cap \{f,g,i,j\} = \emptyset \end{cases} \\
 C[a,e|f,g,i,j] &= \min \begin{cases} C[a+1,e|f,g,i,j], & \text{if } a+1 \notin \{e,f,g,i,j\} \\ C'[a,e-1|f,g,i,j], & \text{if } e-1 \notin \{a,f,g,i,j\} \\ C[a+1,e-1|f,g,i,j] + \Delta G(a,e) & \text{if } \{a+1,e-1\} \cap \{f,g,i,j\} = \emptyset, \\ D'[a,e+1|f,g,i,j] \end{cases} \\
 D[b,d,f,g,i,j] &= \min_c (C_{\text{ax}}[c,d-1,f,g-1] + C_{\text{ax}}[b,e-1,i,j-1])
 \end{aligned}$$



General algorithm for Fatgraph MFE folding problem
Correct for any input sequence (+ C/C++ Code generation)

Complexity: $O(n^{tw})$ or $O(n^{tw+1})$ for simple energy models
 $O(n^{tw+1})$ for full Turner model

Kissing hairpins: an example




MFE folding w.r.t. shadow = Find embedding of motifs **anchors** into RNA:

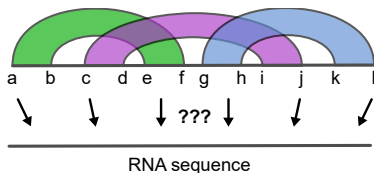
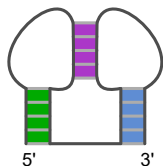
- ▶ **Consistency**: Consecutive anchors should be assigned increasing positions
- ▶ **Helices scoring**: 4 extremities jointly seen, or (inner | outer)ward progression

Option 1: Brute force 

$$MFE := \min_{a < b < c < d < \dots < l} \Delta G(a, b, e, f) + \Delta G(c, d, i, j) + \Delta G(g, h, k, l)$$

→ $O(n^{12})$ time complexity 

Kissing hairpins: an example

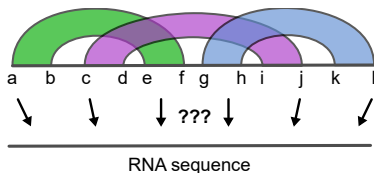
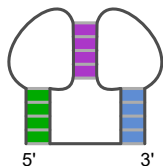


Option 2: Left to right strategy, starting from $(a, l) \rightarrow MFE := \min_{a < l} A(a, l)$

Add anchors from left to right, **forget** unnecessary anchors:

$$A(a, l) = \min_{a < b < l} B(a, b, l)$$

Kissing hairpins: an example

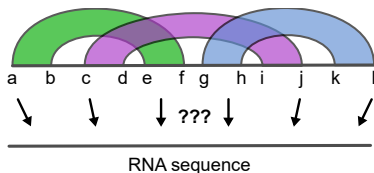
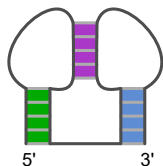


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$$A(a, l) = \min_{a < b < l} B(a, b, l) \quad B(a, b, l) = \min_{b < c < l} C(a, b, c, l)$$

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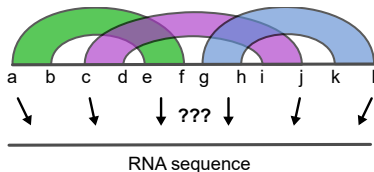
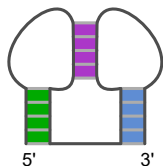


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$$D(a, b, c, d, l) = \min_{d < e < l} E(a, b, c, d, e, l)$$

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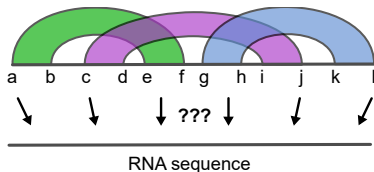
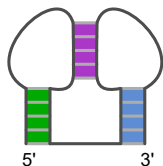


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$$D(a, b, c, d, l) = \min_{d < e < l} E(a, b, c, d, e, l) \quad E(a, b, c, d, e, l) = \min_{e < f < l} F(\underline{a}, \underline{b}, c, d, \underline{e}, f, l) + \Delta G(a, b, e, f)$$

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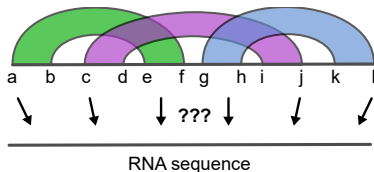
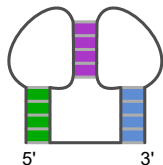


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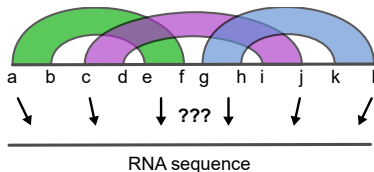
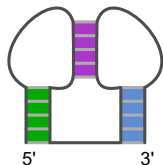


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 F(c, d, f, l) &= \min_{f < g < l} G(c, d, f, g, l) & G(c, d, f, g, l) &= \min_{g < h < l} H(c, d, f, g, h, l)
 \end{aligned}$$

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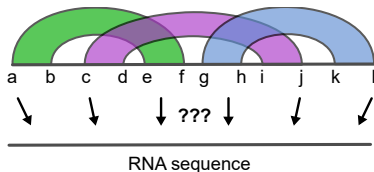
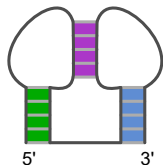


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 F(c, d, f, l) &= \min_{f < g < l} G(c, d, f, g, l) & G(c, d, f, g, l) &= \min_{g < h < l} H(c, d, f, g, h, l) \\
 H(c, d, f, g, h, l) &= \min_{h < i < l} I(c, d, f, g, h, i, l)
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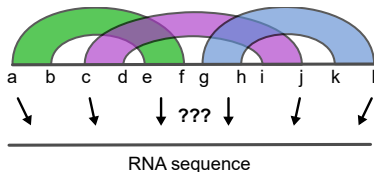
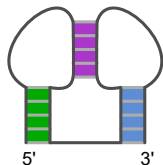


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 \end{aligned}$$

Kissing hairpins: an example



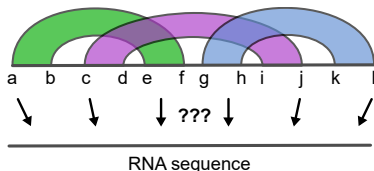
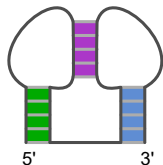
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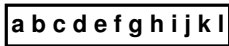
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 H(c, d, f, g, h, l) &= \min_{h < i < l} I(c, d, f, g, h, i, l) & I(c, d, f, g, h, i, l) &= \min_{i < j < l} J(\mathbf{c}, \mathbf{d}, f, g, h, \mathbf{i}, j, l) + \Delta G(c, d, i, j) \\
 J(f, g, h, j, l) &= \min_{j < k < l} \Delta G(g, h, k, l)
 \end{aligned}$$

$\rightarrow O(n^8)$ time complexity (meh!), can we do better?

Treewidth and tree decomposition(s)



Option 1: Brute force $MFE := \min_{a < b < \dots < l} \Delta G(a, b, e, f) + \dots \rightarrow$



Option 2: Left to right

$$MFE := \min_{a < l} A(a, l)$$

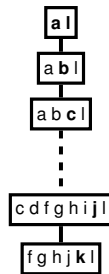
$$A(a, l) = \min_{a < b < l} B(a, b, l)$$

$$B(a, b, l) = \min_{b < c < l} C(a, b, c, l)$$

⋮

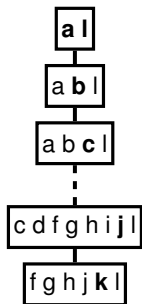
$$I(c, d, f, g, h, i, l) = \min_{i < j < l} J(f, g, h, j, l) + \Delta G(c, d, i, j)$$

$$J(f, g, h, j, l) = \min_{j < k < l} \Delta G(g, h, k, l)$$



Treewidth and tree decomposition

abcdefghijkl



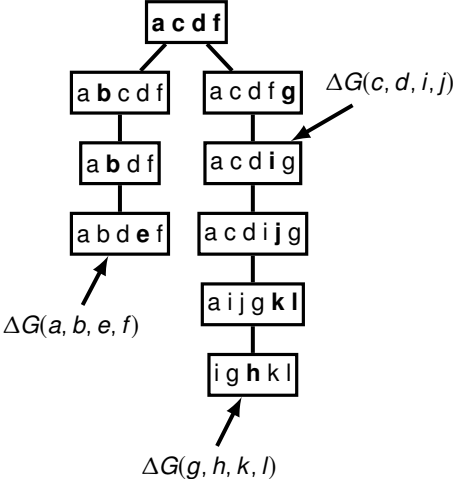
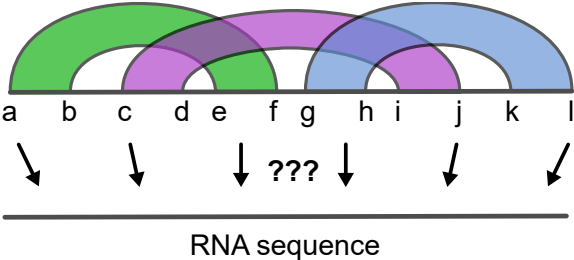
Definition: A **tree decomposition** for $G = (V, E)$ is a tree T over bags $\{X_i\}_i$, $X_i \subseteq V$, such that

- ▶ Any $v \in V$ appears in some bag X_i
- ▶ \forall edge $(u, v) \in E$, \exists bag X_i such that $\{u, v\} \subseteq X_i$
- ▶ For any $v \in V$, the restriction of T to bags that contain v is a (connected) subtree

Treewidth $tw = \text{Size of largest bag} - 1$

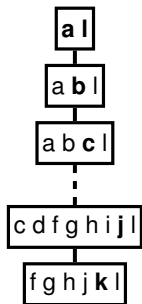
DP scheme for MFE anchors mapping in $O((n + |E|) \cdot n^{tw+1})$
(XP algorithm, NP-hard from k -clique, probably not FPT)

Kissing hairpins: Alternative decomposition



Treewidth and tree decomposition

abcdefghijkl



Definition: A **tree decomposition** for $G = (V, E)$ is a tree T over bags $\{X_i\}_i$, $X_i \subseteq V$, such that

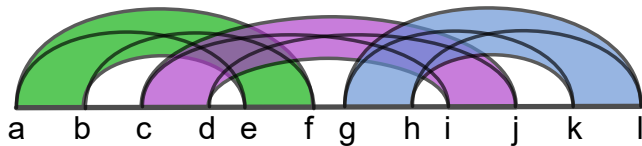
- ▶ Any $v \in V$ appears in some bag X_i
- ▶ \forall edge $(u, v) \in E$, \exists bag X_i such that $\{u, v\} \subseteq X_i$
- ▶ For any $v \in V$, the restriction of T to bags that contain v is a (connected) subtree

Treewidth $tw =$ Size of largest bag $- 1$

Theorem (Bodlaender *et al*): OPT (min treewidth) decomposition can be computed in time $O(n \cdot 2^{O(tw^3)})$

\Rightarrow Optimal* DP schemes for MFE from OPT tree dec.??

Towards general (unbounded) structures



Property: Presence of bags for (4 anchors) helices could be ensured by cliques. . .



Helices can be generated/scored inwards/outwards, saving $O(n)$ time/space
⇒ Instantiating shadow enables tree dec. to benefit from speedup

Problem: How to find generalizable tree decomposition/prevent shortcut?

Five base pairs (BPs) is all you need

Definitions:

- ▶ **Structure space** $\mathcal{S}_{\mathcal{F}}$ of fatgraph \mathcal{F} : (infinite) set of structures factoring into \mathcal{F} ;
- ▶ **Minimal expansion** $C_{\mathcal{F}}$ of \mathcal{F} : Structure with each helix expanded into 5 BPs.



Theorem: Contracting 5+ ladders to 5 base pairs preserves treewidth

Bound is tight as reduction to 4 may reduce treewidth

Corollary: $C_{\mathcal{F}}$ has treewidth larger or equal to any structure in $\mathcal{S}_{\mathcal{F}}$

Intuition: Exploit tree dec. of $C_{\mathcal{F}}$ to make general statements about folding over $\mathcal{S}_{\mathcal{F}}$

From canonical structures to DP algorithms

Theorem: Tree Decomposition of minimal expansion can be transformed into a TD (same width) partitioning helices into **diagonals** and **cliques**

- ▶ **Cliques** = bags featuring 4 helix anchors
 - ▶ **Diagonals** = *triangulated* helices, amenable to inward/outward helix extension
 - ▶ **Transitionals** = other bags, faithfully/boringly propagating anchor values
- + **Generic DP rules** for diagonals and cliques helices contribute energies under BP, Stacking or Turner models

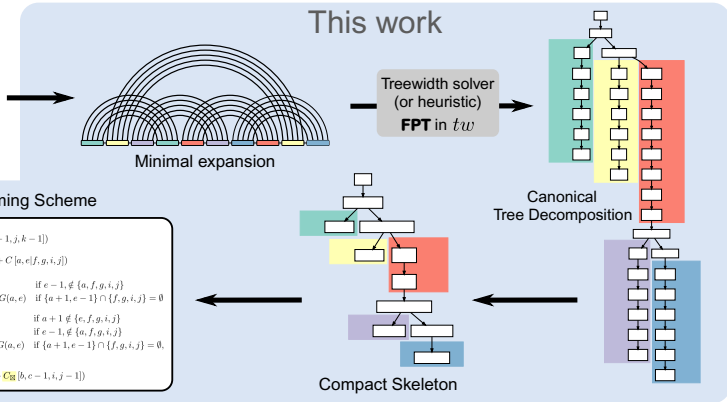
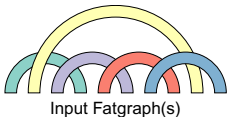
Corollary: MFE folding over the structure space factoring into a given fatgraph \mathcal{F} can be solved in complexity $O(n^{tw+1})$

Putting everything together

PK pattern(s) of interest (e.g. 3D models)



Abstracted as ↓




$$A = \min_{a,g,h,j,k} (B[a,g,h,j] + C_{\alpha}[g,h-1,j,k-1])$$

$$B[a,g,h,j] = \min_{e,f,i} (C_{\alpha}[e,f-1,h,i-1] + C[a,e|f,g,i,j])$$

$$C_{\alpha}[a,e|f,g,i,j] = \min \begin{cases} C'[a,e-1|f,g,i,j], & \text{if } e-1 \notin \{a,f,g,i,j\} \\ C[a+1,e-1|f,g,i,j] + \Delta G(a,e) & \text{if } \{a+1,e-1\} \cap \{f,g,i,j\} = \emptyset \end{cases}$$

$$C_{\beta}[a,e|f,g,i,j] = \min \begin{cases} C[a+1,e|f,g,i,j], & \text{if } a+1 \notin \{e,f,g,i,j\} \\ C'[a,e-1|f,g,i,j], & \text{if } e-1 \notin \{a,f,g,i,j\} \\ C[a+1,e-1|f,g,i,j] + \Delta G(a,e) & \text{if } \{a+1,e-1\} \cap \{f,g,i,j\} = \emptyset, \\ D'[a,e+1|f,g,i,j] & \end{cases}$$

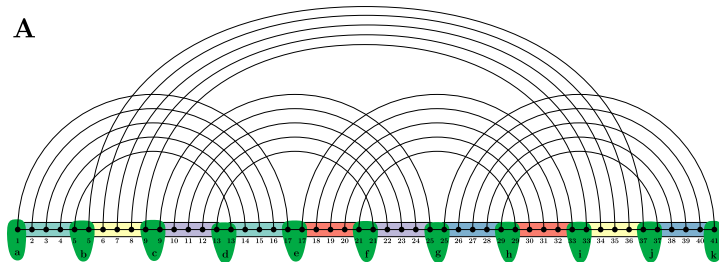
$$D[b,d,f,g,i,j] = \min_c (C_{\alpha}[c,d-1,f,g-1] + C_{\beta}[b,e-1,i,j-1])$$

 General algorithm for Fatgraph MFE folding problem
Correct for any input sequence (+ C/C++ Code generation)

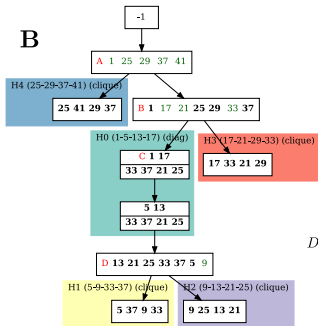
Complexity: $O(n^{tw})$ or $O(n^{tw+1})$ for simple energy models
 $O(n^{tw+1})$ for full Turner model

Example

A



B



C

$$A = \min_{a,g,h,j,k} (B[a, g, h, j] + C_{\boxtimes}[g, h - 1, j, k - 1])$$

$$B[a, g, h, j] = \min_{e,f,i} (C_{\boxtimes}[e, f - 1, h, i - 1] + C[a, e|f, g, i, j])$$

$$C[a, e|f, g, i, j] = \min \begin{cases} C[a + 1, e|f, g, i, j], \\ C[a, e - 1|f, g, i, j], \\ C[a + 1, e - 1|f, g, i, j] + \Delta G(a, e), \\ D[a, e + 1, f, g, i, j] \end{cases}$$

$$D[b, d, f, g, i, j] = \min_c (C_{\boxtimes}[c, d - 1, f, g - 1] + C_{\boxtimes}[b, c - 1, i, j - 1])$$

Some results

Type	Fatgraph	Treewidth	Complexities	
			Full Turner	All others
H-type	([])	4	$O(n^5)$	$O(n^4)$
Kissing hairpins	([]) ([])	4	$O(n^5)$	$O(n^4)$
“L” [Reidys et al, 2011]	([{ }]] }	5	$O(n^6)$	$O(n^6)$
“M” [Reidys et al, 2011]	([{ }] (] })	5	$O(n^6)$	$O(n^6)$
4-clique	([{ < }]] } >	5	$O(n^6)$	$O(n^6)$
5-clique	([{ < A]] } } > a	5	$O(n^6)$	$O(n^6)$
5-chain	({ [] (] [] }]	6	$O(n^7)$	$O(n^7)$

Extensions

- ▶ Embedding PKs/fatgraphs occurrences in 2D centric search spaces
→ Simply add a **ghost edge**, and *voilà*: DP scheme now ready for inclusion within `RNAfold` closed structure table
- ▶ Computing **partition function**/thermodynamic quantities
Generated recursions already **unambiguous** so $(\min, +) \rightarrow (\sum, \times)$ gives \mathcal{Z}
Multiple fatgraphs → Disjoint search spaces
Inside/outside (BP probabilities) obtainable with (a little) more sweat
- ▶ **Recursive pseudoknots**: Consecutive anchors *seen* together
→ Possibility to insert other 2D/PK structures in *unpaired* regions
If non-recursive & affine energy model for PK unpaired regions, merge consecutive anchors (Gotoh trick) for **reduced treewidth**
- ▶ **RNA-RNA interactions** have fatgraphs too!

Musings

- ▶ Optimality of complexities?
For which search space? Lower bounds are hard. . .
- ▶ Polluting conformation spaces! Konformationsraumverschmutzung???
Monkeys & Typewriters → Adding PK motif implies exponential growth of \mathcal{Z}
Geometry: Terminal PKs are OK, recursive PKs are dangerous
- ▶ Tree decomposition vs Parsing (fight!)

Acknowledgments



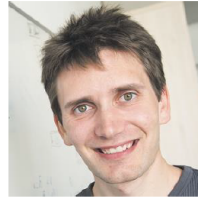
Sebastian Will



Sarah Berkemer



Bertrand Marchand



Laurent Bulteau

+ Ronny (!!) and all members of PaRNAssus ANR/FWF project